Solving Non Linear Function with Two Variables by Using Particle Swarm Optimization Algorithm

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Abstract
The meaning of the Particle Swarm Optimization (PSO) refers to a relatively new family of algorithms that may be used to find optimal (or near optimal) solutions to numerical and qualitative problems.

The genetic algorithm (GA) is an adaptive search method that has the ability for a smart search to find the best solution and to reduce the number of trials and time required for obtaining the optimal solution.

The aim of this paper is to use the PSO to solve some kinds of two variables function which submits to optimize function filed. We investigate a comparison study between PSO and GA to this kind of problems. The experimental results reported will shed more light into which algorithm is best in solving optimization problems.

The work shows the iteration results obtained with implementation in Delphi version 6.0 visual programming language exploiting the object oriented tools of this language.

حل معادلة غير خطية ذات متغيرين باستخدام خوارزمية أمثلية السرب الجزيئي

الخلاصة

أفضل أمثلية السرب الحزيمي (PSO) تشير إلى إيجاد حل مثالي (أو أقرب إلى المثالي) للمسائل المثلية والكئية، وهي طريقة متشابهة لها القابلية على أجراء Genetic Algorithm (GA) بحث كفء لإيجاد الحل الأفضل وتحليل عدد المحولات الزمن المطلوب للحصول على الحل الأمثل.

البحث يهدف إلى استخدام أمثلية السرب الجزيئي (PSO) لحل بعض أنواع الدوال التي تعتمد متغيرين الخاضعة إلى حل أمثلية الدوال. وقد تم تحقق دراسة مقارنة بين طريقة (PSO) والخوارزمية الجزيئية لحل هذا النوع من المسائل. ان النتائج العملية المستخدمة من البحث تسلط الضوء على أي الخوارزمتين أفضل في حل مسائل أمثلية الدوال. لقد نفذ البرنامج الخاص بالدراسة بلغة دلفي (Delphi) من الجيل السادس، وهي من لغات البرمجة المرنة.

1. Introduction

Genetic algorithms (GAs) are a part of evolutionary computing, which is a rapidly growing area of artificial intelligence. GAs are inspired by Darwin's theory about evolution. Simply said, solution to a problem solved by GAs is evolved.

GAs were first suggested by John Holland and developed by him and his students and colleagues in the
seventies of last century. This lead to Holland's book “Adoption in Natural and Artificial Systems” published in 1975 [1]. Over the last twenty years of the last century, it has been used to solve a wide range of search, optimization and machine learning problems. Thus, the GA is an iteration procedure, which maintains a constant size population of candidate solution [1]. In 1992 John Koza has used GA to evolve programs to perform certain tasks. He called his method “genetic programming” (GP) [2].

One of the important new learning methods is the Particle Swarm Optimization (PSO), which is simple in concept, has few parameters to adjust and easy to implement. PSO has found applications in a lot of areas. In general, all the application areas that the other evolutionary techniques are good at are good application areas for PSO [3].

In 1995, Kennedy J. and Eberhart R. [4], introduced a concept for the optimization of nonlinear functions using particle swarm methodology. The evolution of several paradigms outlined, and an implementation of one of the paradigms had been discussed.

In 1999, Eberhart R.C. and Hu X. [5], arranged a new method for the analysis of human tremor using PSO which is used to evolve a Neural Network (NN) that distinguishes between normal subject and those with tremor.

In 2004, Shi Y. [3], surveyed the research and development of PSO in five categories: algorithms, topology, parameters, hybrid PSO algorithms and applications. There are certainly other research works on PSO which are not included here due to the space limitation.

2. Genetic Algorithm

Genetic Algorithms (GAs) are search algorithms based on the mechanics of natural selection and natural genetics. They combine survival of the fittest among string structures with a structured yet randomized information exchange to form a search algorithm with some of the innovative flair of human search. In every generation, a new set of artificial creatures (strings) is created using bits and pieces of the fittest of the old; an occasional new part is tried for good measure. While randomized GAs are no simple random walk, They efficiently exploit historical information to speculate on new search point with expected improved performance [6].


There is a large class of interesting problems for which no reasonably fast algorithms have been developed. Given such a hard optimization problem it is often possible to find an efficient algorithm whose solution is approximately optimal. We discuss the basic features of a GA for optimization of a simple function. Let

\[ f(x_1, x_2) = 21.5 + x_1 \cdot \sin(4\pi x_1) + x_2 \cdot \sin(20\pi x_2) \] (1)

where \(-3.0 \leq x_1 \leq 12.1\) and \(4.1 \leq x_2 \leq 5.8\).

Since x1, x2 are real numbers, this implies that the search space can be huge and that traditional methods can fail to find optimal solution [7].

4. Implementation of GA in Optimization of a Function Problem

4.1. Problem Representation [8]

To apply the GA for maximizing f(x1,x2) in (1), a genetic representation of solution to the problem must be appropriately chosen.
first. The Simple GA uses the binary representation in which each point \((x_1, x_2)\) is described by a chromosome vector coded as a binary string. We use a binary vector as a chromosome to represent real values of the variable \(x\), the length of the vector depends on the required precision, which in this example, is six places after the decimal point.

The domain of the variable \(x_1\) has length 15.1; the precision requirement implies that the range \([-3.0, 12.1]\) should be divided into at least \(15.1 \times 10000\) equal size ranges. This means that 18 bits are required as the first part of the chromosome:
\[
2^{17} < 151000 < 2^{18}
\]

The domain of the variable \(x_2\) has length 1.7; the precision requirement implies that the range \([4.1, 5.8]\) should divided into at least \(1.7 \times 10000\) equal size ranges. This means that 15 bits are required as the second part of the chromosome:
\[
2^{14} < 17000 < 2^{15}
\]

The total length of a chromosome (solution vector) is then \(m = 18 + 15 = 33\) bits;
the first 18 bits code \(x_1\) and the remaining 15 bits from (19–33) code \(x_2\) [8].

Let us consider an example chromosome:
\((01000101011000111110010100010)\) or responds to \((x_1, x_2) = (-2.334465, 4.699438)\).

The fitness value for this chromosome is:
\[
f(-2.334465, 4.699438) = 26.566770.
\]

To optimize the function \(f\) using GA, we create a population of \(\text{pop\_size}\) chromosomes. All 33 bits in all chromosomes are initialized randomly.

Evaluation function for binary vector \(v\) is equivalent to, the function \(f\):
\[
eval(v) = f(x_1, x_2) \quad (2)
\]

where the chromosome \(v\) represents the 33 digits string.

During the evaluation phase we decode each chromosome and calculate the fitness function from \((x_1, x_2)\) values just decoded.

For example, the two chromosomes:
\(v_1 = 10010101000001111110100111111\)
\(v_2 = 11100010010110010100101100011010\),
Correspond to values \(x_1\) and \(x_2\) respectively. Consequently, the evaluation function would rate them as follows:
\[
eval(v_1) = f(11.161431, 4.954643) = 34.237697
\]
\[
eval(v_2) = f(10.953948, 7.767766) = 33.832967
\]

Clearly, the chromosome \(v_1\) is the best of the two chromosomes, since its evaluation returns the highest value.

1. Selection Operator
Roulette wheel is chosen to sum up the fitness’ of all individuals and to calculate each individual percentage of the total fitness. The percentage of the total fitness of each individual is then used as the probability to select \(N\) individuals from the set population and copy them into the set selected-parents.

2. The Mating Crossover Operator
Individuals from the set selected-parents are mated to generate offspring’s for the next generation. The two parents generate two offspring’s using a crossover operation. For this example, to illustrate the crossover operator on chromosome with a crossover with probability \(P_c\), we generate random integer number \(\text{pos}\) from the range
The number (pos) indicates the position of the crossing point. Suppose the pair of chromosomes is:

\[
\begin{align*}
v_1 &= (1001100000011111010011011111), \\
v_2 &= (0001000110010000001011110101),
\end{align*}
\]
and the generated number (pos)=9. These chromosomes are cut after the 9th bit and the remaining 24 bits exchange position: the two resulting offspring's are:

\[
\begin{align*}
v_1' &= (100110100011000100001011101101111), \\
v_2' &= (0000100000011111101001101111111111).
\end{align*}
\]

**Mutation Operator**

Mutation is a random change of one or more genes (positions in a chromosome) with a probability equal to the mutation rate \( P_m \), a gene is changed/swapped, i.e. \( 0 \rightarrow 1 \) and \( 1 \rightarrow 0 \). The probability for a mutation is usually kept small. Assume that the fifth gene from the \( v_2 \) chromosome was selected for a mutation. Since the fifth gene in this chromosome is 1, it would be flipped into 0. So the chromosome \( v_2' \) after this mutation would be:

\[
v_2' = (0000000000011111101001101111).
\]

2. **Genetic Parameters**

For this particular problem, Michalewicz [8] used the following parameters: population size \( \text{pop}_\text{size}=20 \), probability of crossover \( c=0.25 \), probability of mutation \( P_m=0.01 \).

4.1 **Experimental Results**

In Table (1) below we provide the generation number for which we noticed the improvement in the evaluation function, together with the value of the function.

For this problem, a simulation has been constructed in order to apply the GA. Using population size \( \text{pop}_\text{size}=20 \), the crossover parameters mentioned above, the following results are being obtained:

\[
v_{\text{max}} = (0100111111111111110110111111),
\]

Which corresponds to a value \( (x_1,x_2)=(12.099251,5.79325) \), and \( f(v_{\text{max}})=35.761033 \).

Notice that the solution \( f(v_{\text{max}})=35.761033 \) is obtained in the generation \( (660) \).

5. **Particle Swarm Optimization (PSO)**

PSO was originally developed by a social-psychologist J. Kennedy and an electrical engineer R. Eberhart in 1995 and emerged from earlier experiments with algorithms that modeled the “flocking behavior” seen in many species of birds. Where birds are attracted to a roosting area in simulations they would begin by flying around with no particular destination and then spontaneously forming flocks until one of the birds flew over the roosting area [9]. PSO has been an increasingly hot topic in the area of computational intelligence. it is yet another optimization algorithm that falls under the soft computing umbrella that over genetic and evolutionary computing algorithms as well [10].

5.1 **Fitness Criterion**

One of these stopping criteria is the fitness function value. The fitness value is related by the kind of the objective function, the PSO can be applied to minimize or maximize this function. In this paper we focused in maximizing the objective function in order to improve the results.
Maximize $f(x_1,x_2) = 21.5 + x_1 \sin(4\pi x_1) + x_2$.
\[
\text{in}(20\pi x_2)
\] (3)
here $-3.0 \leq x_1 \leq 12.1$ and $4.1 \leq x_2 \leq 5.8$.

5.2. PSO Algorithm [3]
The PSO algorithm depends on its implementation in the following two relations:
\[\begin{align*}
\text{vid} &= w \cdot \text{vid} + c_1 \cdot r_1 \cdot (\text{bpid} - \text{pid}) + c_2 \cdot r_2 \cdot (\text{pgd} - \text{pid}) \quad (4a) \\
\text{xid} &= \text{xid} + \text{vid} \quad (4b)
\end{align*}\]
where \(c_1\) and \(c_2\) are positive constants, \(r_1\) and \(r_2\) are random functions in the range \([0,1]\), \(\text{pi}=(\text{pi}_1,\text{pi}_2,\ldots,\text{pid})\) represents the \(i\)th particle; \(\text{bpi}=(\text{bpi}_1,\text{bpi}_2,\ldots,\text{bpid})\) represents the best previous position (the position giving the best fitness value) of the \(i\)th particle; the symbol \(g\) represents the index of the best particle among all the particles in the population, \(\text{vi}=(\text{vi}_1,\text{vi}_2,\ldots,\text{vid})\) represents the rate of the position change (velocity) for particle \(i\) [3].

The original procedure for implementing PSO is as follows:
1. Initialize a population of particles with random positions and velocities on \(d\)-dimensions in the problem space.
2. PSO operation includes:
   a. For each particle, evaluate the desired optimization fitness function in \(d\) variables.
   b. Compare particle’s fitness evaluation with its pbest. If current value is better than pbest, then set pbest equal to the current value, and bpi equals to the current location pi.
   c. Identify the particle in the neighborhood with the best success so far, and assign it index to the variable \(g\).
   d. Change the velocity and position of the particle according to equation (4a) and (4b).
3. Loop to step (2) until a criterion is met.

Like the other evolutionary algorithms, a PSO algorithm is a population based on search algorithm with random initialization, and there is an interaction among population members. Unlike the other evolutionary algorithms, in PSO, each particle flies through the solution space, and has the ability to remember its previous best position, survives from generation to another. The flow chart of PSO algorithm is shown in Figure (1) [11].

5.3. The Parameters of PSO [12]
A number of factors will affect the performance of the PSO. These factors are called PSO parameters, these parameters are:
1. Number of particles in the swarm affects the run-time significantly, thus a balance between variety (more particles) and speed (less particles) must be sought.
2. Maximum velocity (vmax) parameter. This parameter limits the maximum jump that a particle can make in one step.
3. The role of the inertia weight \(w\), in equation (4a), is considered critical for the PSO’s convergence behavior. The inertia weight is employed to control the impact of the previous history of velocities on the current one.
4. The parameters \(c_1\) and \(c_2\), in equation (4a), are not critical for PSO’s convergence. However, proper fine-tuning may result in faster convergence and alleviation of local minima, \(c_1\) than a social parameter \(c_2\) but with \(c_1 + c_2 = 4\).
5. The parameters r1 and r2 are used to maintain the diversity of the population, and they are uniformly distributed in the range [0,1].

6. Implementation of PSO

In this paper we will try to apply PSO algorithm in optimizing a function. This problem was chosen according to different factors such as representation of the problem (which have a great influence on PSO algorithm) which can be applied more efficiently. Furthermore, this problem has been chosen since it owns a high complexity (the size and the shape of the search space), which cannot be solved using traditional known searches, like exhaustive search method.

6.1. Problem Representation

To apply the PSO for maximizing f(x), a genetic representation of solution to the problem must be appropriately chosen first. PSO can use the binary representation in which each point is described by a (position), BP (best position) and v (velocity) vector coded as real values range [-1,1]. Then when the value of each component is less or equal to 0 it is converted to 0 else it is considered as 1 so it is changed to a binary vector as a string of bits to represent real values of the variable x, the length of the vector depends on the required precision, which in this example, is six places after the decimal point as we do in representation of each chromosome of GA.

6.2. Initial Population

To optimize the function f using PSO, we create a population of pop size=10 or 20 particles. All 33 real values converted to 33 corresponding 33-bits which are initialized randomly. For example:

bp=(-0.31,0.14,0.52,-0.43,-0.78,-0.01,…,0.1,-0.32,0.59,-0.72,0.005,0.86)

of 33 real components converted to the following binary string:

v = (0,1,1,0,0,0,…,1,0,1,0,1,1).

6.3. Experimental Results

For this particular problem, we use α population size pop_size=10, c1=c2=1, α∈[0.4,0.9], max=0.5 and vmin=-vmax. And r1& r2∈[0,1] are chosen randomly withevery generation. In Table (2) we provide the vector bp, generation number for which we noticed the improvement in the evaluation function together with the value of the function, evolution function and values of the variables x.

For this problem, a simulation has been constructed in order to apply PSO, using the parameters mentioned above; the following results are being obtained after 20 generation from 500 generation:

\[ v_{max} = (011011111111111111011011111111111) \]

which corresponds to a value \((x1,x2)=(11.990843,5.292858)\),

and \( f(v_{max})= 35.498874 \).

Our main development in the following section.

7. Developing of Applying Real PSO Process

In analytic study of Tables (1) and (2), we noticed that in applying the GA we gain better results from binary PSO with respect to value of evolution function \( f(x1,x2) \) \((f(x1,x2)= 35.761033 \text{ for GA} \) and \( f(x1,x2) = 35.498874 \text{ for PSO})\, but PSO is more better in the number of generation (NG=660 for A while NG=20 for PSO) and the process time. In this section we are developing the application of PSO.
algorithm to gain more efficient method to improve the results.

The improvement of applying PSO is as follows:

The component of the vectors p and bp are still real and need no change to binary; its just required no more than 2 real variable numbers, these values of x_1 and x_2 say, will considered to be the component of the mentioned vectors.

The new algorithm real PSO is as follows:

**Algorithm**

**START.**

**INPUT:** c_1=1, pop_size=10, v_max=0.5, gen.=500.

**INITIALIZATION:**

- c_2=c_1, v_min=-v_max.
- Random real position of all particles.
- Random real velocity of all particles.
- Computing of fitness values for each particle.

**PROCESS:** For i=1 to gen.

- Evaluating the particles.
- Computing of fitness values for each particle.
- Best_Fit<=particle_Fit.

**END.**

**OUTPUT:** Best_Fit

**END.**

By substituting each value of x_1 and x_2 in equation (1) we can get the evaluation function.

For PSO problem, a simulation has been constructed in order to apply PSO, using the parameters mentioned above; the following results are being obtained after 14 generations:

(x_1, x_2)=(12.1, 5.8), and f(v_max)= 35.762019.

**8. Conclusions**

1. The reason that the GA is better than the binary PSO is that the GA gives more varieties in changing a single gene of the chromosome because of crossover and mutation processes.

2. The real PSO is better than the GA and binary PSO to approach the good fitness result in less process time and in less number of generations.

3. Further suggestions; we can replace the types of binary representation by the real representation when applying PSO.

4. We suggest making a hybrid between GA and PSO in solving optimization of function to improve approaching solution in less time and less number of generations.

5. We suggest using more complicated function including more than two variables to get solutions to these complicated and applicable functions.

**References**


Table (1) Results of 1000 generations for optimization of a function problem

<table>
<thead>
<tr>
<th>Chromosome</th>
<th>Gen. No.</th>
<th>Evolution Function</th>
<th>Variables $x_1$</th>
<th>$x_2$</th>
</tr>
</thead>
<tbody>
<tr>
<td>01000100101101000010001001011010</td>
<td>0</td>
<td>26.566769</td>
<td>2.334464</td>
<td>4.699438</td>
</tr>
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<td>4.849531</td>
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<td>660</td>
<td>35.761033</td>
<td>12.099251</td>
<td>5.799325</td>
</tr>
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</table>
Table (2) Results of 500 generations for optimization of a function using binary PSO.

<table>
<thead>
<tr>
<th>Corresponding string of bp vector</th>
<th>Gen. No.</th>
<th>Evolution Function</th>
<th>Variables $x_1$</th>
<th>$x_2$</th>
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<tbody>
<tr>
<td>11101101110011011010111010</td>
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<td>990843</td>
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</table>

Table (3) the results of applying real PSO of optimization to the function.

<table>
<thead>
<tr>
<th>Gen. No.</th>
<th>Evolution Function</th>
<th>Variables $x_1$</th>
<th>$x_2$</th>
</tr>
</thead>
<tbody>
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<td>14</td>
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<td>12.100000</td>
<td>5.800000</td>
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</table>
Table (4) Shows a comparison with the three Algorithms (Bin.GA, Bin. PSO and Real PSO).

<table>
<thead>
<tr>
<th>Algorithm</th>
<th>Gen. No.</th>
<th>Evolution Function</th>
<th>Variables</th>
</tr>
</thead>
<tbody>
<tr>
<td>Bin. GA</td>
<td>660</td>
<td>35.761033</td>
<td>x₁</td>
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<td>Bin. PSO</td>
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<td>12.099251</td>
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<tr>
<td>Real PSO</td>
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<td>35.762019</td>
<td>12.100000</td>
</tr>
</tbody>
</table>

Evaluate the fitness of each particle

- fitness < bp<sub>id</sub>
  - Yes: Renew bp<sub>id</sub> and position
  - No: bp<sub>id</sub> < pg<sub>d</sub>
    - Yes: Renew pg<sub>d</sub>
    - No: v<sub>id</sub> = w * vi<sub>d</sub> + c<sub>1</sub> * r<sub>1</sub> * (bp<sub>id</sub> - pi<sub>d</sub>) + c<sub>2</sub> * r<sub>2</sub> * (pg<sub>d</sub> - xi<sub>d</sub>)

p<sub>id</sub> = p<sub>id</sub> + v<sub>id</sub>

- No: criterion end?
  - Yes: End

Figure (1) Flowchart of PSO Algorithm.