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1<sup>st</sup> class

Mathematics

الرياضيات

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## Chapter One

Consider an arbitrary system of equation in unknown as:

$$AX = B \dots\dots\dots(1)$$

$$\left. \begin{array}{l} a_{11}X_1 + a_{12}X_2 + a_{13}X_3 + \dots\dots\dots + a_{1n}X_n \\ a_{21}X_1 + a_{22}X_2 + a_{23}X_3 + \dots\dots\dots + a_{2n}X_n = b_1 \\ a_{31}X_1 + a_{32}X_2 + a_{33}X_3 + \dots\dots\dots + a_{3n}X_n = b_2 \\ \dots\dots\dots \\ a_{m1}X_1 + a_{m2}X_2 + a_{m3}X_3 + \dots\dots\dots + a_{mn}X_n = b_m \end{array} \right\} \dots\dots\dots(2)$$

The coefficient of the variables and constant terms can be put in the form:

$$\begin{pmatrix} a_{11} & a_{12} & a_{1n} \\ a_{21} & a_{22} & a_{2n} \\ \dots\dots\dots \\ a_{m1} & a_{m2} & a_{mn} \end{pmatrix}_{m \times n} \begin{pmatrix} x_1 \\ x_2 \\ \dots\dots\dots \\ x_n \end{pmatrix}_{n \times 1} = \begin{pmatrix} b_1 \\ b_2 \\ \dots\dots\dots \\ b_m \end{pmatrix}_{m \times 1} \dots\dots\dots(3)$$

Let the form

$$\begin{pmatrix} a_{11} & a_{12} & a_{1n} \\ a_{21} & a_{22} & a_{2n} \\ \dots\dots\dots \\ a_{m1} & a_{m2} & a_{mn} \end{pmatrix} = A = (a_{ij}) \dots\dots\dots(4)$$

Is called (mxn) matrix and donated this matrix by:

$[a_{ij}]$   $i = 1, 2, \dots\dots\dots m$  and  $j = 1, 2, \dots\dots\dots n$ .

We say that is an (mxn) matrix or **تكلمة**

The matrix of order (mxn) it has m rows and n columns.

For example the first row is  $(a_{11}, a_{12}, a_{1n})$

And the first column is  $\begin{pmatrix} a_{11} \\ a_{21} \\ \dots\dots\dots \\ a_{m1} \end{pmatrix}$

$(a_{ij})$  denote the element of matrix. Lying in the  $i$  – th row and  $j$  – th column, and we call this element as the  $(i,j)$  - th element of this matrix

Also  $\begin{pmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{pmatrix}_{n \times 1}$  is  $(n \times 1)$  [n rows and columns]

$\begin{pmatrix} b_1 \\ b_2 \\ \vdots \\ b_m \end{pmatrix}_{m \times 1}$  Is  $(m \times 1)$  [m rows and 1 column]

### Sub – Matrix:

Let A be matrix in (4) then the sub-matrix of A is another matrix of A denoted by deleting rows and (or) column of A.

$$\text{Let } A = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix}$$

Find the sub-matrix of A with order  $(2 \times 3)$  any sub-matrix of A denoted by

$$\text{deleting any row of } A \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{pmatrix}, \begin{pmatrix} 1 & 2 & 3 \\ 7 & 8 & 9 \end{pmatrix}, \begin{pmatrix} 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix}$$

### Definition 1.1:

Two  $(m \times n)$  matrices  $A = [a_{ij}]$   $(m \times n)$  and  $B = [b_{ij}]$   $(m \times n)$  are said to be equal if and only if:

$$a_{ij} = b_{ij} \text{ for } i = 1, 2, \dots, m \text{ and } j = 1, 2, \dots, n$$

Thus two matrices are equal if and only if:

- i. They have the same dimension, and
- ii. All their corresponding elements are equal for example:

$$\begin{bmatrix} 2 & 0 & -1 \\ 3 & 5 & 2 \end{bmatrix} = \begin{bmatrix} \frac{4}{2} & 0(7) & -2+1 \\ 3 & \frac{20}{4} & 2 \end{bmatrix}$$

Definition 1.2

If  $A = [a_{ij}]_{m \times n}$  and  $B = [b_{ij}]_{m \times n}$  are  $m \times n$  matrix their sum is the  $m \times n$  matrix  $A+B = [a_{ij} + b_{ij}]_{m \times n}$ .

In other words if two matrices have the same dimension, they may be added by addition corresponding elements. For example if:

$$A = \begin{pmatrix} 2 & -7 \\ -3 & 4 \end{pmatrix} \text{ and } B = \begin{pmatrix} -5 & 0 \\ 1 & 6 \end{pmatrix}$$

Then

$$A+B = \begin{pmatrix} 3+(-5) & -7+0 \\ -3+1 & 4+6 \end{pmatrix} = \begin{pmatrix} -2 & -7 \\ -2 & 10 \end{pmatrix}$$

Additions of matrices, like equality of matrices is defined only of matrices have same dimension.

Theorem 1.1:

Addition of matrices is commutative and associative, that is if A, B and C are matrices having the same dimension then:

$$A + B = B + A \text{ (commutative)}$$

$$A + (B + C) = (A + B) + C \text{ (associative)}$$

### Definition 1.3

The product of a scalar  $K$  and an  $m \times n$  matrix  $A = [a_{ij}]$  is the  $m \times n$  matrix  $KA = [ka_{ij}]$  for example:

$$6 \begin{pmatrix} -1 & 0 & 7 \\ 5 & 2 & -11 \end{pmatrix} = \begin{pmatrix} 6(-1) & 6(0) & 6(7) \\ 6(5) & 6(2) & 6(-11) \end{pmatrix} = \begin{pmatrix} -6 & 0 & 42 \\ 30 & 12 & -66 \end{pmatrix}$$

### Application of Matrices

#### Definition 1.4:

If  $A = [a_{ij}]$  is an  $m \times n$  matrix and  $B = [b_{jk}]$  is an  $n \times p$  matrix, the product  $AB$  is the  $m \times p$  matrix  $C = [c_{ik}]$  in which

$$c_{ik} = \sum_{j=1}^n a_{ij} b_{jk}$$

Example 1: if  $A = \begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \end{pmatrix}_{2 \times 3}$  and  $B = \begin{pmatrix} b_{11} \\ b_{21} \\ b_{22} \end{pmatrix}_{3 \times 1}$

$$AB = \begin{pmatrix} a_{11}b_{11} + a_{12}b_{21} + a_{13}b_{22} \\ a_{21}b_{11} + a_{22}b_{21} + a_{23}b_{22} \end{pmatrix}_{2 \times 1}$$

Example 2: Let  $A = \begin{pmatrix} 2 & 3 \\ -1 & 4 \\ 5 & -2 \end{pmatrix}_{3 \times 2}$  and  $B = \begin{pmatrix} 3 & 1 & 4 & -5 \\ -2 & 0 & 3 & 4 \end{pmatrix}_{2 \times 4}$

$$AB = \begin{pmatrix} 0 & 2 & 17 & 2 \\ -11 & -1 & 8 & 21 \\ 19 & 5 & 14 & -33 \end{pmatrix}_{3 \times 4}$$

**Note 1.1:**

1 – in general if A and B are two matrices. Then A B may not be equal of

BA. For example  $A = \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}$   $B = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \rightarrow AB = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$  and  $BA = \begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}$   
 $\therefore AB \neq BA$

2 – if A B is defined then its not necessary that B A must also be defined.

For example. If A is of order (2×3) and B of order (3×1) then clearly A B is define, but B A is not defined.

**1.3 Different Types of matrices:**

1 – Row Matrix: A matrix which has exactly one row is called row matrix.

For example (1, 2, 3, 4) is row matrix

2 – Column Matrix: A matrix which has exactly one column is called a

column matrix for example  $\begin{pmatrix} 5 \\ 6 \\ 7 \end{pmatrix}$  is a column matrix.

3 – Square Matrix: A matrix in which the number of row is equal to the

number of columns is called a square matrix for example  $\begin{pmatrix} 1 & 2 \\ 3 & 4 \end{pmatrix}$  is a 2×2

square matrix.

A matrix (A) (n×n) A is said to be order or to be an n-square matrix.

4 - Null or Zero Matrix: A matrix each of whose elements is zero is called null matrix or zero matrix, for example  $\begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$  is a (2×3) null matrix.

5 – Diagonal Matrix: the elements  $a_{ii}$  are called diagonal of a square matrix  $(a_{11} \ a_{22} \ - \ a_{nn})$  constitute its main diagonal A square matrix whose every element other than diagonal elements is zero is called a diagonal matrix for

Example:  $\begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 2 \end{pmatrix}$  or  $\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$

6 – Scalar Matrix: A diagonal matrix, whose diagonal elements are equal, is called a scalar matrix.

For example  $\begin{pmatrix} 5 & 0 \\ 0 & 5 \end{pmatrix}, \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}, \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$  are scalar matrix

7 – Identity Matrix: A diagonal matrix whose diagonal elements are all equal to 1 (unity) is called identity matrix or (unit matrix). And denoted by  $I_n$  for

Example  $I_2 = \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}$

**Note1.2:** if A is (m×n) matrix, it is easily to define that  $AI_n = A$  and also  $I_m A = A$

**Ex:** Find  $AI$  and  $IA$  when  $A = \begin{pmatrix} 3 & 7 & 2 \\ 1 & -1 & 3 \end{pmatrix}$

$$\text{Solution: IA} \longrightarrow \begin{pmatrix} 1 & 0 \\ 0 & 1 \end{pmatrix}_{2 \times 2} \begin{pmatrix} 3 & 7 & 2 \\ 1 & -4 & 3 \end{pmatrix}_{2 \times 3} = \begin{pmatrix} 3 & 7 & 2 \\ 1 & -4 & 3 \end{pmatrix}_{2 \times 3}$$

$$\text{And AI} = \begin{pmatrix} 3 & 7 & 2 \\ 1 & -4 & 3 \end{pmatrix}_{2 \times 3} = \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}_{3 \times 3} = \begin{pmatrix} 3 & 7 & 2 \\ 1 & -4 & 3 \end{pmatrix}_{2 \times 3}$$

8 – Triangular Matrix: A square matrix  $(a_{ij})$  whose element  $a_{ij} = 0$  whenever  $j < i$  is called a lower triangular matrix. Similarly a square matrix  $(a_{ij})$  whose element  $a_{ij} = 0$  whenever  $j > i$  is called an upper triangular matrix.

For example:  $\begin{pmatrix} 1 & 0 & 0 \\ 4 & 5 & 0 \\ 7 & 8 & 9 \end{pmatrix}$ ,  $\begin{pmatrix} 1 & 0 \\ 2 & 1 \end{pmatrix}$  are lower triangular matrix

And

$\begin{pmatrix} 1 & 2 & 3 \\ 0 & 4 & 5 \\ 0 & 0 & 6 \end{pmatrix}$ ,  $\begin{pmatrix} 1 & 2 \\ 0 & 3 \end{pmatrix}$ , are upper triangular

Definition 1.4:

### Transpose of matrix

The transpose of an  $m \times n$  matrix  $A$  is the  $n \times m$  matrix denoted by  $A^T$ , formed by interchanging the rows and columns of  $A$  the  $i$ th rows of  $A$  is the  $i$ th columns in  $A^T$ .

For Example:  $A = \begin{pmatrix} 1 & 2 & 3 \\ 0 & 1 & -1 \end{pmatrix}_{2 \times 3}$   $A^T = \begin{pmatrix} 1 & 0 \\ 2 & 1 \\ 3 & -1 \end{pmatrix}_{3 \times 2}$

9 – Symmetric Matrix: A square matrix  $A$  such that  $A = A^T$  is called symmetric matrix i.e.  $A$  is a symmetric matrix if and only if  $a_{ij} = a_{ji}$  for all element.

$$8 \quad \begin{pmatrix} 0 & 1 & 2 \\ 1 & 2 & 3 \\ 2 & 3 & 4 \end{pmatrix}$$



For Example:  $\textcircled{a} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 3 \end{pmatrix}, \textcircled{b}$

10 – Skew symmetric Matrix: A square matrix A such that  $A = -A^T$  is called that A is skew symmetric matrix. i.e A is skew matrix  $\longleftrightarrow a_{ji} = -a_{ij}$  for all element of A.

The following are examples of symmetric and skew – symmetric matrices respectively

$$(a) \begin{pmatrix} 0 & 1 & 2 \\ 1 & 2 & 3 \\ 2 & 3 & 4 \end{pmatrix}, (b) \begin{pmatrix} 0 & 1 & 2 \\ -1 & 0 & 3 \\ -2 & -3 & 0 \end{pmatrix}$$

(a) symmetric

(b) Skew – symmetric.

Note the fact that the main diagonal element of a skew – symmetric matrix must all be Zero

11 – Determinates: To every square matrix that is assigned a specific number called the determinates of the matrix.

(a) Determinates of order one: write  $\det(A)$  or  $|A|$  for detrimental of the matrix A. it is a number assigned to square matrix only.

The determinant of  $(1 \times 1)$  matrix (a) is the number a itself  $\det(a) = a$ .

(c) Determinants of order two: the determinant of the  $2 \times 2$ . matrix  $\begin{pmatrix} a & b \\ c & d \end{pmatrix}$

Is denoted and defined as follows:  $\begin{vmatrix} a & b \\ c & d \end{vmatrix} = ad - bc$

Theorem 1.2: determinant of a product of matrices is the product of the determinant of the matrices is the product of the determinant of the matrices  $\det(A B) = \det(A) \cdot \det(B)$   $\det(A + B) \neq \det a + \det B$

(C) Determinates of order three:

(i) the determinant of matrix is defined as follows:

$$\begin{vmatrix} + & - & + \\ a_{11} & a_{22} & a_{23} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} = a_{11} \begin{vmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{vmatrix} - a_{12} \begin{vmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{vmatrix} + a_{13} \begin{vmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{vmatrix}$$

(ii) Consider the (3×3) matrix  $\begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix}$

$$= a_{11} a_{22} a_{33} + a_{21} a_{22} a_{31} + a_{13} a_{21} a_{32} - a_{31} a_{22} a_{13} - a_{32} a_{23} a_{11} - a_{33} a_{21} a_{12}.$$

Show that the diagram papering below where the first two columns are rewritten to the right of the matrix.

Theorem 1.3:

A matrix is invertible if and only if its determinant is not Zero usually a matrix is said to be singular if determinant is zero and non singular it otherwise.

### 1.5 prosperities of Determinants

- (1)  $\det A = \det A^T$  where  $A^T$  is the transpose of  $A$ .
- (2) if any two rows (or two columns) of a determinates are interchanged the value of determinants is multiplied by -1.
- (3) if all elements in row (or column) of a square matrix are zero.

Then  $\det (A) = 0$

(4) if two parallel column (rows) of square matrix A are equal then  $\det(A) = 0$

(5) if all the elements of one row (or one column) of a determinant are multiplied by the same factor K. the value of the new determinant is K times the given det.

Example;

$$\begin{pmatrix} 4 & 6 & 1 \\ 3 & -9 & 2 \\ -1 & 12 & 3 \end{pmatrix} = \begin{pmatrix} 4 & 2.3 & 1 \\ 3 & -3.3 & 2 \\ -1 & 4.3 & 3 \end{pmatrix}$$

$$= 3 \begin{pmatrix} 4 & 2 & 1 \\ 3 & -3 & 2 \\ -1 & 4 & 3 \end{pmatrix}$$

Example:  $\begin{pmatrix} 1 & 0 & 4 \\ -2 & 5 & -8 \\ 3 & 6 & 12 \end{pmatrix} = 4 \begin{pmatrix} 1 & 0 & 1 \\ -2 & 5 & -2 \\ 3 & 6 & 3 \end{pmatrix} = 0$

(6) if to each element of a selected row (or column) of a square matrix = k times. The corresponding element of another selected row (or column) is added.

Example:  $\begin{vmatrix} 2 & 0 & 2 \\ 1 & -1 & +1 \\ 3 & 0 & 2 \end{vmatrix} = -1 \begin{vmatrix} 2 & 2 \\ 3 & 2 \end{vmatrix} = 2$

$2 \times \text{row (1)} + \text{row (3)} \begin{vmatrix} 2 & 0 & 2 \\ 1 & -1 & 1 \\ 7 & 0 & 6 \end{vmatrix} = -1 \begin{vmatrix} 2 & 2 \\ 7 & 6 \end{vmatrix} = 2$

(7) if any row or column contain zero elements and only one element not zero then the determinant will reduced by elementary the row and column if the specified element indeterminate.

**1.6 Rank of Matrix:** we defined the rank of any matrix as that the order of the largest square sub-matrix of a whose determinant not zero (det of sub-matrix  $\neq 0$ )

Example: Let  $A = \begin{pmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{pmatrix}$  find the rank of A

$$1 \times 9 \times 5 + 2 \times 6 \times 7 + 3 \times 4 \times 8 - 3 \times 5 \times 7 - 1 \times 6 \times 8 - 2 \times 4 \times 9 = 0$$

Since  $|A|$  of order 3 Rank  $\neq 3$

Since  $\begin{vmatrix} 1 & 2 \\ 4 & 5 \end{vmatrix} = -3 \neq 0$  the rank  $\neq 2$

1.7 Minor of matrix: Let  $A = \begin{pmatrix} a_{11} & a_{12} & a_{1n} \\ a_{21} & a_{22} & a_{2n} \\ a_{n1} & a_{n2} & a_{nn} \end{pmatrix}$  (4)

Is the square matrix of order n then the determinant of any square sub-matrix of a with order (n-1) obtained by deleting row and column is called the minor of A and denoted by  $M_{ij}$ .

1.8 Cofactor of matrix: Let A be square matrix in (4) with  $m_{ij}$  which is the minors of its. Then the Cofactor of a defined by  $C_{ij} = (-1)^{i+j} M_{ij}$

Example: Let  $A = \begin{pmatrix} -2 & 4 & 1 \\ 4 & 5 & 7 \\ -6 & 1 & 0 \end{pmatrix}$  find the minor and the cofactor of element 7.

Solution: The minor of element 7 is

$$M_{23} = \det \begin{pmatrix} -2 & 4 \\ -6 & 1 \end{pmatrix} = \begin{vmatrix} -2 & 4 \\ -6 & 1 \end{vmatrix} = 22$$

i.e (denoted by take the square sub-matrix by deleting the second rows and third column in A).

the Cofactor of 7 is

$$C_{23} = (-1)^{2+3} M_{23} = (-1)^{2+3} \begin{vmatrix} -2 & 4 \\ -6 & 1 \end{vmatrix} = -22$$

1.9 Adjoint of matrix: Let matrix A in (4) then the transposed of matrix of cofactor of this matrix is called adjoint of A, adjoint A = transposed matrix of Cofactor.

The inverse of matrix: Let A be square matrix. Then inverse of matrix

{Where A is non-singular matrix} denoted by  $A^{-1}$  and  $A^{-1} = \frac{1}{\det A} \text{adj}(A)$

1.0 method to find the inverse of A: To find the inverse of matrix we must find the following:

- (i) the matrix of minor of elements of A.
- (ii) the Cofactor of minor of elements of A
- (iii) the adjoint of A .

$$\text{then } A^{-1} = \frac{1}{|A|} \text{adj}A$$

$$\text{Example: let } A = \begin{pmatrix} 2 & 3 & -4 \\ 1 & 2 & 3 \\ 3 & -1 & -1 \end{pmatrix} \text{ Find } A^{-1}$$

$$(1) \text{ Minors of A is } M_{ij} = \begin{pmatrix} 1 & -10 & -7 \\ -7 & 10 & -11 \\ 17 & 10 & 1 \end{pmatrix}$$

$$(2) \text{ Cofactor of A is } (-1)^{ij} M_{ij} = \begin{pmatrix} 1 & 10 & -7 \\ 7 & 10 & 11 \\ 17 & -10 & 1 \end{pmatrix}$$

$$(3) \text{ Adj of A} = \begin{pmatrix} 1 & 7 & 17 \\ 10 & 10 & -10 \\ -7 & 11 & 1 \end{pmatrix}.$$

$$(4) \det = 60$$

$$A^{-1} = \frac{1}{60} \begin{pmatrix} 1 & 7 & 17 \\ 10 & 10 & -10 \\ -7 & 11 & 1 \end{pmatrix}.$$

### 1.11 Properties of Matrix Multiplication:

1 –  $(KA) B = K (AB) = A (KB)$   $K$  is any number

2 –  $A (BC) = (AB) C$

3 –  $(A + B) C = AC + BC$

4 –  $C (A + B) = CA + CB$

5 –  $AB \neq BA$  (in general)

For example: Let  $A = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix}$  and  $B = \begin{pmatrix} 0 & 1 \\ 1 & 1 \end{pmatrix}$

$$A B = \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$$

$$B A = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 1 & 0 \end{pmatrix}$$

$A B \neq B A$

6 –  $A B = 0$  but not necessarily  $A = 0$  or  $B = 0$

For Example:  $A = \begin{pmatrix} 1 & 1 \\ 2 & 2 \end{pmatrix}, B = \begin{pmatrix} -1 & +1 \\ +1 & -1 \end{pmatrix}$

$$A B = \begin{pmatrix} 1 & 1 \\ 2 & 2 \end{pmatrix} \begin{pmatrix} -1 & 1 \\ 1 & -1 \end{pmatrix} = \begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$$

$A \neq 0, B \neq 0$

But

$A B = 0$

$$7 - \begin{pmatrix} C & 0 & 0 \\ 0 & C & 0 \\ 0 & 0 & C \end{pmatrix} = C \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

8 –  $A I = I A = A$  where  $I$  is identity matrix

$$9 - (A B)^T = B^T A^T$$

$$10 - A^{-1} A = A.A^{-1} = I$$

### 1.12 Cramer's Rule

Let the system of linear question as

$$\left. \begin{array}{l} a_{11} x_1 + a_{12} x_2 = b_1 \\ a_{21} x_1 + a_{22} x_2 = b_2 \end{array} \right\} \rightarrow (i)$$

The system (i) can put in the form:

$$\begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \end{pmatrix} \rightarrow (ii)$$

$$\text{If } D = \begin{vmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{vmatrix} \neq 0$$

Then the system (ii) has a unique solution, and Cramer's rule state that it may be found from the formulas:

$$x_1 = \frac{\begin{vmatrix} b_1 & a_{12} \\ b_2 & a_{22} \end{vmatrix}}{D}, \quad x_2 = \frac{\begin{vmatrix} a_{11} & b_1 \\ a_{21} & b_2 \end{vmatrix}}{D}$$

Example: solve the system

$$3x_1 - x_2 = 9$$

$$x_1 + 2x_2 = -4$$

So, the system can put in the form

$$\begin{pmatrix} 3 & -1 \\ 1 & 2 \end{pmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{pmatrix} 9 \\ -4 \end{pmatrix}$$

$$D = \begin{vmatrix} 3 & -1 \\ 1 & 2 \end{vmatrix} = 7, \quad \chi_1 = \frac{\begin{vmatrix} 9 & -1 \\ -4 & 2 \end{vmatrix}}{D} = \frac{14}{7} = 2$$

$$\chi_2 = \frac{\begin{vmatrix} 3 & 9 \\ 1 & -4 \end{vmatrix}}{D} = \frac{21}{7} = 3$$

Let the following system in the unknowns:

$$a_{11} \chi_1 + a_{12} \chi_2 + a_{13} \chi_3 = b_1$$

$$a_{21} \chi_1 + a_{22} \chi_2 + a_{23} \chi_3 = b_2$$

$$a_{31} \chi_1 + a_{32} \chi_2 + a_{33} \chi_3 = b_3$$

The system (I) can be put in the form:

$$\begin{pmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{pmatrix} \begin{pmatrix} \chi_1 \\ \chi_2 \\ \chi_3 \end{pmatrix} = \begin{pmatrix} b_1 \\ b_2 \\ b_3 \end{pmatrix} \quad (\text{II})$$

$$\text{If } D = \begin{vmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{vmatrix} \neq 0$$

The system has a unique solution, given by Cramer's rule:

$$\chi_1 = \frac{1}{D} \begin{vmatrix} b_1 & a_{12} & a_{13} \\ b_2 & a_{22} & a_{23} \\ b_3 & a_{32} & a_{33} \end{vmatrix}, \quad \chi_2 = \frac{1}{D} \begin{vmatrix} a_{11} & b_1 & a_{13} \\ a_{21} & b_2 & a_{23} \\ a_{31} & b_3 & a_{33} \end{vmatrix}, \quad \chi_3 = \frac{1}{D} \begin{vmatrix} a_{11} & a_{12} & b_1 \\ a_{21} & a_{22} & b_2 \\ a_{31} & a_{32} & b_3 \end{vmatrix}$$

Example: solve the system

$$X_1 + 3X_2 - 2X_3 = 11$$

$$4X_1 - 2X_2 + X_3 = -15$$

$$3X_1 + 4X_2 - X_3 = 3$$



By cramer's rule.

$$\text{The system (1) become } \begin{pmatrix} 1 & 3 & -2 \\ 4 & -2 & 1 \\ 3 & 4 & -1 \end{pmatrix} \begin{bmatrix} X_1 \\ X_2 \\ X_3 \end{bmatrix} = \begin{pmatrix} 11 \\ -15 \\ 3 \end{pmatrix}$$

$$\text{Since } D = \det = \begin{vmatrix} 1 & 3 & -2 \\ 4 & -2 & 1 \\ 3 & 4 & -1 \end{vmatrix} = -25$$

Cramer's rule gives the solution:

$$x_1 = \frac{\begin{vmatrix} 11 & 3 & -2 \\ -15 & -2 & 1 \\ 3 & 4 & -1 \end{vmatrix}}{-25} = \frac{50}{-25} = -2$$

$$x_2 = \frac{\begin{vmatrix} 1 & 11 & -2 \\ 4 & -15 & 1 \\ 3 & 3 & -1 \end{vmatrix}}{-25} = \frac{-25}{-25} = 1$$

$$x_3 = \frac{\begin{vmatrix} 1 & 3 & 11 \\ 4 & -2 & -15 \\ 3 & 4 & -1 \end{vmatrix}}{-25} = \frac{125}{-25} = -5$$

## Chapter Two

### Function Numbers:

1 – N = set of natural numbers

$$N = \{1, 2, 3, 4, \dots\}$$

2 – I = set of integers

$$= \{\dots, -3, -2, -1, 0, 1, 2, 3, \dots\}$$

Note that: NCI

3 – A = set of rational numbers

$$= \left[ \chi : \chi = \frac{p}{q} \text{ } p \text{ and } q \text{ are integers } q \neq 0 \right]$$

Ex:  $\frac{3}{2}, -\frac{4}{5}, \frac{3}{1}, \frac{-7}{1}$

Note that: ICA

4 – B = set of irrational numbers

$$= \{X : X \text{ is not arational number}\}$$

Ex:  $\sqrt{2}, \sqrt{3}, -\sqrt{7}$

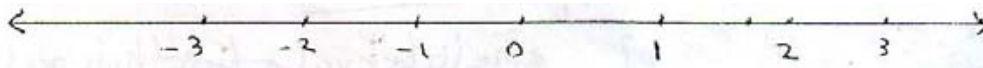
5 – R: set of real numbers

= set of all rational and irrational numbers

Note that

$$R = A \cup B$$

Note: the set of real numbers is represented by a line called a line of numbers:



(ii) NCR, ICR, ACR, BCR

### Intervals

The set of values that a variable  $\chi$  may take on is called the domain of  $\chi$ .

The domains of the variables in many applications of calculus are intervals like those shows below.

- **open intervals**

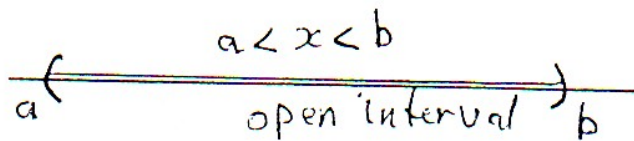
is the set of all real numbers that lie strictly between two fixed numbers a and b:

**In symbols**

$$a < \chi < b \text{ or } (a, b)$$

**In words**

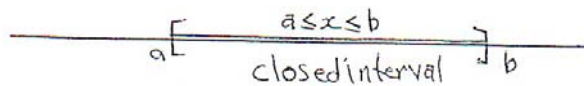
The open interval a b



- Closed Intervals contain both endpoints:

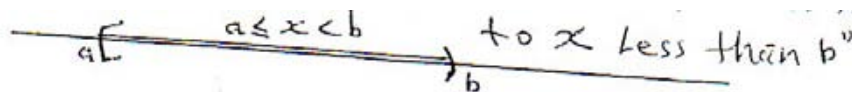
**In symbols**  
 $a \leq x \leq b$  or  $[a, b]$

**In words**  
 the closed interval a b



- Half – open intervals contain one but not both end points:

**In symbols:**  $a \leq x < b$  or  $[a, b)$       **in words** ' the interval a less than or equal To x less than b



$a < x \leq b$  or  $(a, b]$       the interval a less than x less than or equal b



Ex. find the domain of

$$1 - Y = \sqrt{1 - X^2}$$

The domain of  $x$  is the closed interval

$$-1 \leq x \leq 1$$

$$2 - Y = \frac{1}{\sqrt{1 - X^2}}$$

The domain for  $x$  is open interval

$$-1 < x < 1 \text{ because } \frac{1}{0} \text{ is not defined}$$

$$B - y = \sqrt{\frac{1}{x} - 1}$$

$$\frac{1}{x} - 1 \geq 0 \text{ or } \frac{1}{x} \geq 1$$

The domain for  $x$  is the half – open  $0 < x \leq 1$

Ex: **the equation**

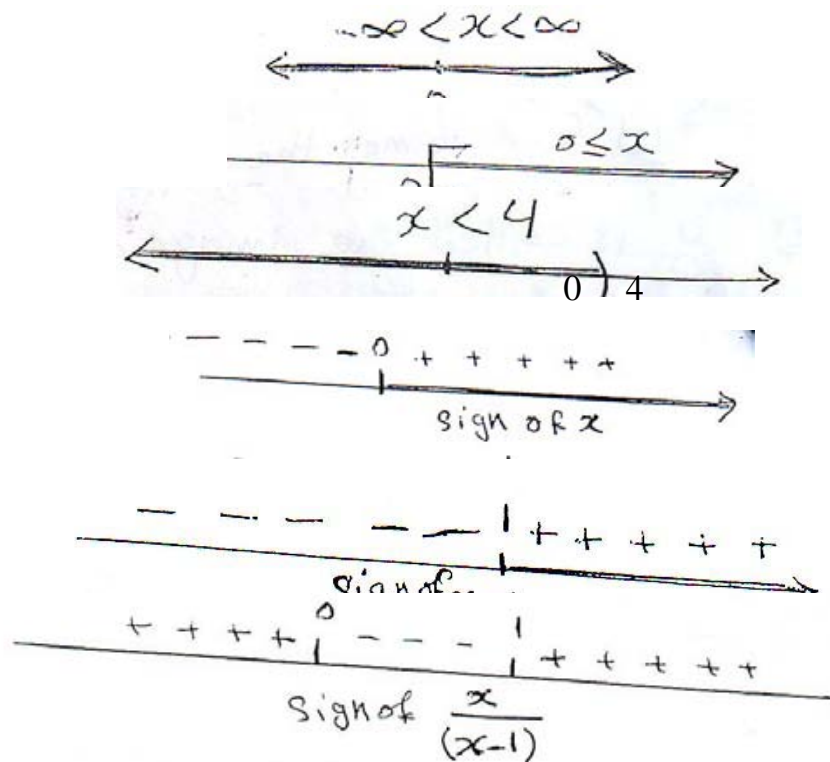
$$Y = x^2$$

$$Y = \sqrt{x}$$

$$Y = \frac{1}{\sqrt{4-x}}$$

$$y = \sqrt{\frac{x}{x-1}}$$

**the domain**



The domain for  $x$  is  $x \leq 0 \cup x > 1$

Definition: A function, say  $f$  is a relation between the elements of two sets say  $A$  and  $B$  such that for every  $x \in A$  there exists one and only one  $Y \in B$  with  $Y = F(X)$ .

The set  $A$  which contain the values of  $x$  is called the domain of function  $F$ .

The set  $B$  which contains the values of  $Y$  corresponding to the values of  $x$  is called the range of the function  $F$ .  $x$  is called the independent variable of the function  $F$ , while  $Y$  is called the dependant variable of  $F$ .

**Note:**

- 1 – Some times the domain is denoted by  $DF$  and the range by  $RF$ .
- 2 –  $Y$  is called the image of  $x$ .

Example: Let the domain of  $\chi$  be the set  $\{0,1,2,3,4\}$ . Assign to each value of  $\chi$  the number  $Y = \chi^2$ . The function so defined is the set of pairs,  $\{ (0,0), (1,1), (2,4), (3,9), (4,16) \}$ .

Example: Let the domain of  $\chi$  be the closed interval

$-2 \leq \chi \leq 2$ . Assign to each value of  $\chi$  the number  $y = \chi^2$ .

The set of order pairs  $(\chi, y)$  such that  $-2 \leq \chi \leq 2$

And  $y = \chi^2$  is a function.

**Note:** Now can describe function by two things:

1 – the domain of the first variable  $\chi$ .

2 – the rule or condition that the pairs  $(\chi, y)$  must satisfy to belong to the function.

**Example:**

The function that pairs with each value of  $\chi$  different from 2 the number

$$\frac{\chi}{\chi-2}$$

$$y = f(\chi) = \frac{\chi}{\chi-2} \quad \chi \neq 2$$

Note 2: Let  $f(\chi)$  and  $g(\chi)$  be two function.

$$1 - (f \pm g)(\chi) = f(\chi) \pm g(\chi)$$

$$2 - (f \cdot g)(\chi) = f(\chi) \cdot g(\chi)$$

$$3 - \left(\frac{f}{g}\right)(\chi) = \frac{f(\chi)}{g(\chi)} \quad \text{if } g(\chi) \neq 0$$

Example: Let  $f(\chi) = \chi + 2, g(\chi) = \sqrt{\chi - 3}$  evaluate

$$f \pm g, f \cdot g \text{ and } \frac{f}{g}$$

So:  $(f \pm g)(x) = f(x) \pm g(x) = x + 2 \pm (\sqrt{x - 3})$

$(f \cdot g)(x) = f(x) \cdot g(x) = (x + 2)(\sqrt{x - 3})$

$\left(\frac{f}{g}\right)(x) = \frac{f(x)}{g(x)} = \frac{x + 2}{\sqrt{x - 3}} \quad \{x : x > 3\}$

**Composition of Function:**

Let  $f(x)$  and  $g(x)$  be two functions

We define:  $(f \circ g)(x) = f(g(x))$

Example: Let  $f(x) = x^2$ ,  $g(x) = x - 7$  evaluate  $f \circ g$  and  $g \circ f$

So:  $(f \circ g)(x) = f[g(x)] = f(x - 7) = (x - 7)^2$

$(g \circ f)(x) = g[f(x)] = g(x^2) = x^2 - 7$

$\therefore f \circ g \neq g \circ f$

**Inverse Function**

Given a function  $F$  with domain  $A$  and the range  $B$ .

The inverse function of  $f$  written  $f^{-1}$ , is a function with domain  $B$  and range

$A$  such that for every  $y \in B$  there exists only  $x \in A$  with  $x = f^{-1}(y)$ .

Note that:  $f^{-1} \neq \frac{1}{f}$

**Polynomials:** A polynomial of degree  $n$  with independent variable, written  $f_n(x)$  or simply  $f(x)$  is an expression of the form:

$f_n(x) = q_0 + a_1x + a_2x^2 + \dots + anx^n \dots \dots (*)$

Where  $q_0, a_1, \dots, a_n$  are constant (numbers).

The degree of polynomial in equation ( \* ) is  $n$  ( the highest power of equation)

Example:

- (i)  $f(x) = 5x$  polynomial of degree one.

(ii)  $f(x) = 3x^5 - 2x + 7$  polynomial of degree five.

(iii)  $F(x) = 8$  polynomial of degree Zero.

**Notes:**

The value of  $x$  which make the polynomial  $f(x) = 0$  are called the roots of the equation ( $f(x) = 0$ )

Example:  $x = 2$  is the root of the polynomial

$$F(x) = x^2 - x - 2$$

Since  $f(2) = 0$

Example:  $F(x)$  Linear function if

$$F(x) = ax + b.$$

**Even Function:**

$F(x)$  is even if  $f(-x) = F(x)$

Example: 1 -  $F(x) = (x)^2$  is even since  $f(-x) = (-x)^2 = (x)^2 = f(x)$

2 -  $F(x) = \cos(x)$  is even because  $f(-x) = \cos(-x) = \cos(x) = f(x)$

**Odd Function:**

If  $f(-x) = -f(x)$  the function is called odd.

Example: 1 -  $f(x) = x^3$  is odd since  $f(-x) = -x^3 = -f(x)$

$$2 - f(x) = \sin(-x) = -\sin X = -f(x).$$

**Trigonometric Function:**

$$1 - \sin \varphi = \frac{a}{c}$$

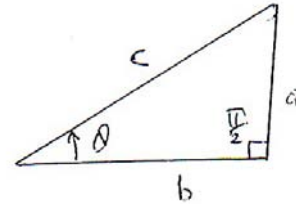
$$2 - \cos \varphi = \frac{b}{c}$$

$$3 - \tan \varphi = \frac{a}{b}$$

$$4 - \cotan \varphi = \frac{1}{\tan \varphi} = \frac{b}{a}$$

$$5 - \sec \varphi = \frac{1}{\cos \varphi} = \frac{c}{b}$$

$$6 - \csc \varphi = \frac{1}{\sin \varphi} = \frac{c}{a}$$



### Relation ships between degrees and radians

$$\varphi \text{ In radius} = \frac{s}{r}$$

$$360^\circ = \frac{2\pi r}{r} = 2\pi \text{ radius}$$

$$1^\circ = \frac{\pi}{180} \text{ radius} = 0.0174 \text{ radian}$$

$$1 \text{ radian} = \frac{180}{\pi} \text{ degree} = 57.29578^\circ$$

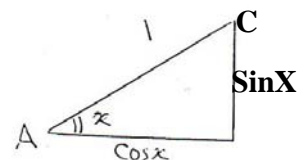
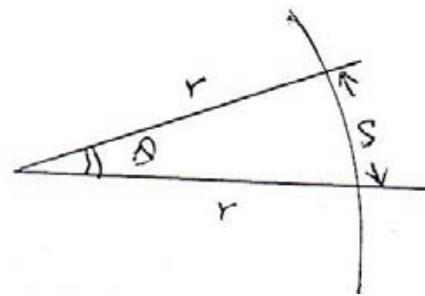
$$\left( \frac{360}{2\pi} \right) = 1 \text{ radian} = 57^\circ.18$$

$$180^\circ = \pi \text{ radians} = 3.14159 - \text{radians}$$

$$1^\circ = \frac{2\pi}{360} = \frac{\pi}{180} \approx 0.001754 \text{ radians}$$

$$\tan \chi = \frac{\sin \chi}{\cos \chi}$$

$$\cot \chi = \frac{\cos \chi}{\sin \chi} = \frac{1}{\tan \chi}$$





**B**

$$\text{Sec } \chi = \frac{1}{\cos \chi}$$

$$\text{Csc } \chi = \frac{1}{\sin \chi}$$

$$\text{Cos}^2 \chi + \text{Sin}^2 \chi = 1$$

$$\tan^2 \chi + 1 = \text{Sec}^2 \chi$$

$$\text{Cot}^2 \chi + 1 = \text{Csc}^2 \chi$$

$$\text{Sin}(\chi \pm y) = \text{Sin} \chi \text{Cos} y \pm \text{Cos} \chi \text{Sin} y$$

$$\text{Cos}(\chi \pm y) = \text{Cos} \chi \text{Cos} y \mp \text{Sin} \chi \text{Sin} y$$

$$\tan(\chi \pm y) = \frac{\tan \chi \pm \tan y}{1 \mp \tan \chi \tan y}$$

$$1 - \text{Sin} A + \text{Sin} B = 2 \text{Sin} \frac{A+B}{2} \text{Cos} \frac{A-B}{2}$$

$$2 - \text{Sin} A - \text{Sin} B = 2 \text{Cos} \frac{A+B}{2} \text{Sin} \frac{A-B}{2}$$

$$3 - \text{Cos} A + \text{Cos} b = 2 \text{Cos} \frac{A+B}{2} \text{Cos} \frac{A-B}{2}$$

$$4 - \text{Cos} A - \text{Cos} B = 2 \text{Sin} \frac{A+B}{2} \text{Sin} \frac{A-B}{2}$$

$$\text{Sin} 2X = 2 \text{Sin} X \text{Cos} X$$

$$\text{Cos}^2 = \text{Cos}^2 X - \text{Sin}^2 X$$

$$= 1 - 2 \text{Sin}^2 X$$

$$= 2 \text{Cos}^2 X - 1$$

$$\text{Cos}^2 x = \frac{1 + \text{Cos}^2 x}{2}$$

$$\text{Sin}^2 x = \frac{1 - \text{Cos}^2 x}{2}$$

$$\text{Sin}(\varphi + 2\pi) = \text{Sin} \varphi$$

$$\text{Cos}(\varphi + 2\pi) = \text{Cos} \varphi$$

$$\tan(\varphi + \pi) = \tan \varphi$$

Degree	0°	30°	45°	60°	90°	180°	270°	360°
$\theta$ radius	0	$\frac{\pi}{6}$	$\frac{\pi}{4}$	$\frac{\pi}{3}$	$\frac{\pi}{2}$	$\pi$	$\frac{3\pi}{2}$	$2\pi$
$\sin \theta$	0	$\frac{1}{2}$	$\frac{1}{\sqrt{2}}$	$\frac{\sqrt{3}}{2}$	1	0	-1	0
$\cos \theta$	1	$\frac{\sqrt{3}}{2}$	$\frac{1}{\sqrt{2}}$	$\frac{1}{2}$	0	-1	0	1
$\tan \theta$	0	$\frac{1}{\sqrt{3}}$	1	$\sqrt{3}$				

$$\cos(\varphi + 2n\pi) = \cos \varphi$$

$$\sin(\varphi + 2n\pi) = \sin \varphi$$

$$\cos(-\varphi) = \cos \varphi$$

$$\sin(-\varphi) = -\sin \varphi$$

$$\cos\left(\frac{\pi}{2} + \varphi\right) = -\sin \varphi$$

$$\sin(\pi - \varphi) = \sin \varphi$$

$$\tan\left(\frac{\pi}{2} + \varphi\right) = -\cot \varphi$$

### Graphs:

The set of points in the plane whose coordinate pairs are also the ordered pairs of function is called the graph of function.

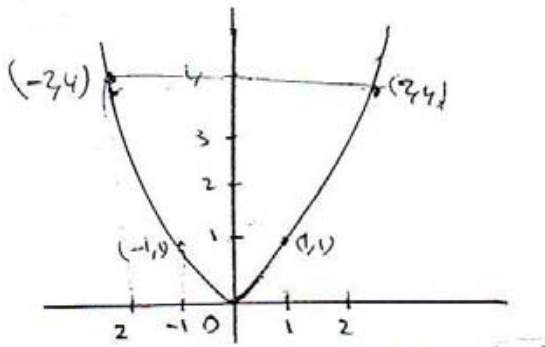
Example: Graph a function we carry out three steps  $y = x^2, -2 \leq x \leq 2$

1 – Make a table of pairs from the function as

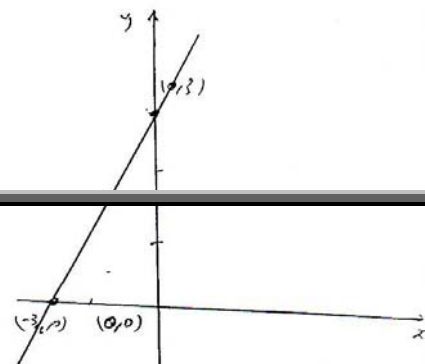
$x$	$y = x^2$	$(x, y)$
-2	4	(-2,4)
-1	1	(-1,1)
0	0	(0,0)
+1	1	(1,1)
2	4	(2,4)

2 – Plot enough of the corresponding points to learn the shape of the graph. Add more pairs to the table if necessary.

3 – Complete the sketch by connecting the points.



Example:  $y = 2x + 3$



<b>X</b>	$y = 2X + 3$	<b>(X,y)</b>
0	3	(0,3)
$-\frac{3}{2}$	0	$(-\frac{3}{2}, 0)$

### Absolute Value:

We define the absolute value function  $y = |x|$ , the function assign every negative number to non-negative, which corresponding points.

The absolute values of X:

$$|X| = \sqrt{X^2} = \begin{cases} x & \text{if } X \geq 0 \\ -x & \text{if } X < 0 \end{cases}$$

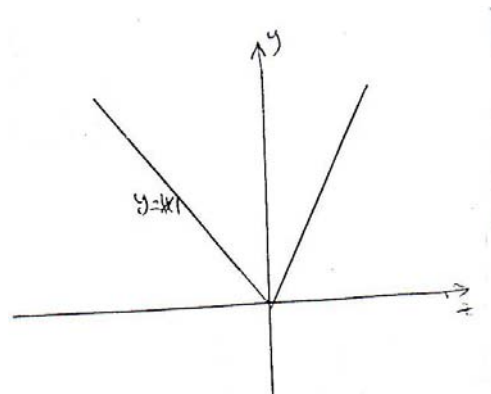
Then:

$$1 - |a.b| = |a|, |b|$$

$$2 - |a + b| \leq |a| + |b|$$

$$3 - |a| \leq C \Leftrightarrow -C \leq a \leq C$$

$$y = f(x) = x$$



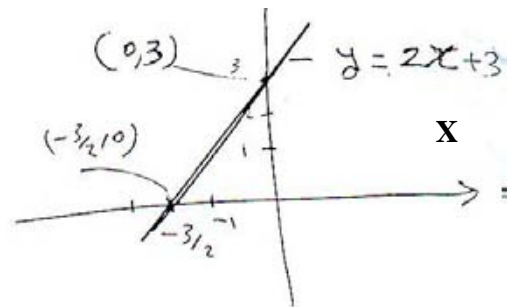
<b>X</b>	<b>y</b>	<b>(X,y)</b>
-1	1	(-1,1)
0	0	(0,0)
1	1	(1,1)

**Example 2:**

$$y = f(x) = ax + b$$

$$y = f(x) = 2x + 3$$

X	y	(X,y)
0	3	(0,3)
$-\frac{3}{2}$	0	$(-\frac{3}{2}, 0)$



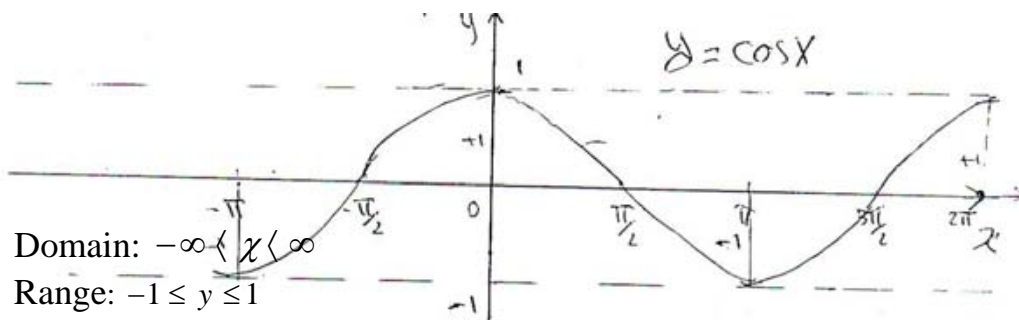
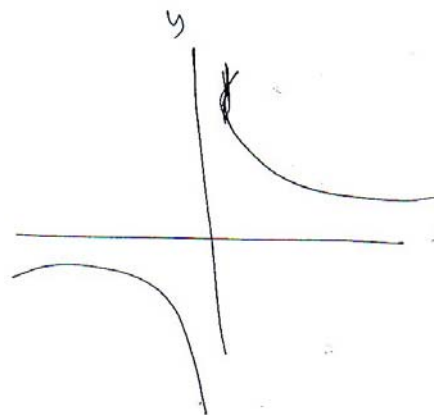
**Example 3:**

$$y = f(x) = \frac{1}{x}$$

X	y	(X,y)
1	1	(1,1)
-1	-1	(-1,-1)
$\frac{1}{2}$	2	$(\frac{1}{2}, 2)$
$\frac{1}{3}$	3	$(\frac{1}{3}, 3)$
2	$\frac{1}{2}$	$(2, \frac{1}{2})$
3	$\frac{1}{3}$	$(3, \frac{1}{3})$

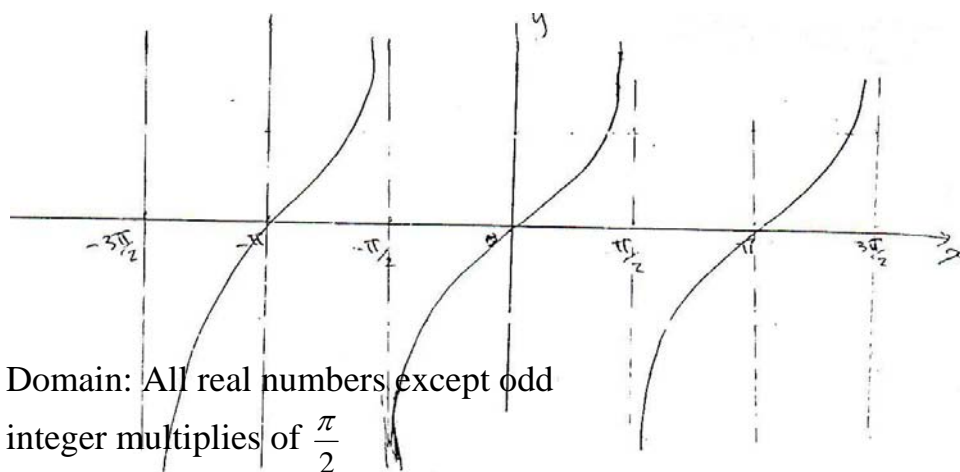
Domain:  $-\infty < x < \infty$

Range:  $-1 \leq y \leq 1$



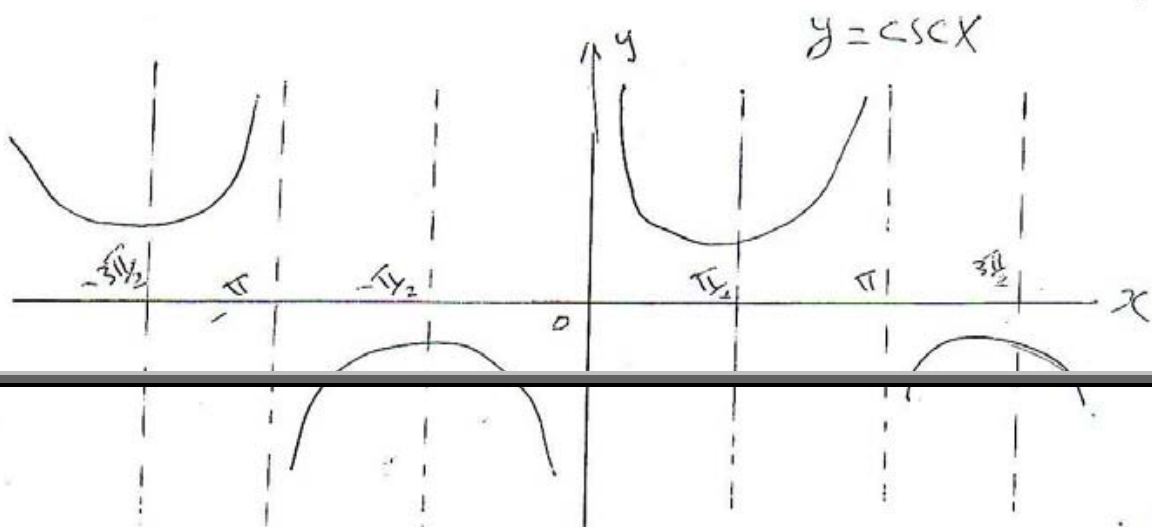
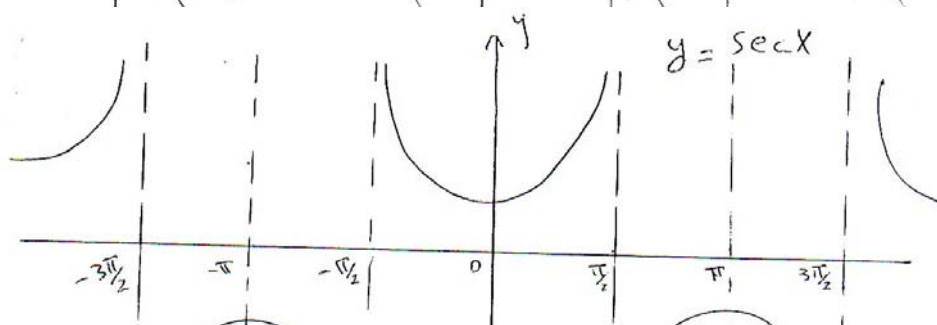
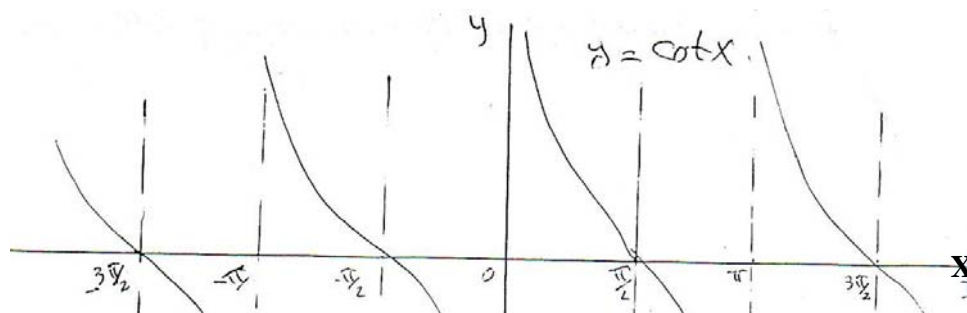
Domain:  $-\infty < x < \infty$

Range:  $-1 \leq y \leq 1$



Domain: All real numbers except odd integer multiples of  $\frac{\pi}{2}$

Range:  $-\infty < y < \infty$



**Limits:**

We say that  $L$  is a right hand limit for  $f(x)$  when  $X$  approaches  $C$  for the right, written

$$\lim_{x \rightarrow C^+} f(x) = L$$

Similarly,  $L$  is the left – hand limit for  $f(x)$  when  $X$  approaches  $C$  for the left, written

$$\lim_{x \rightarrow C^-} f(x) = L,$$

Then  $\lim_{x \rightarrow C} f(x) = L,$

$$\lim_{x \rightarrow C} f(x) = L \text{ if and only if } \lim_{x \rightarrow C^+} f(x) = L \text{ and } \lim_{x \rightarrow C^-} f(x) = L$$

Example:

$$\lim_{x \rightarrow 1} \frac{x^2 - 1}{x - 1} = \lim_{x \rightarrow 1} \frac{(x - 1)(x + 1)}{x - 1}$$

$$x \rightarrow 1 \quad x \rightarrow 1$$

$$\lim_{x \rightarrow 1} x + 1 = 1 + 1 = 2$$

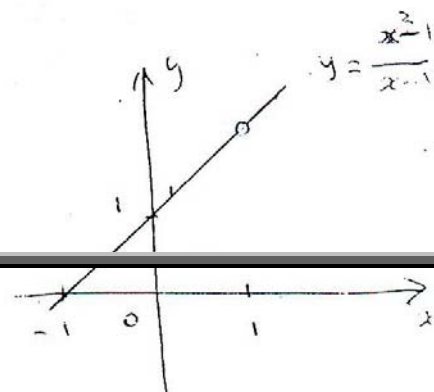
$$x \rightarrow 1$$

Theorem 1

$$\text{If } \lim_{x \rightarrow c} f(x) = L_1, \lim_{x \rightarrow c} g(x) = L_2$$

Then

$$\lim_{x \rightarrow c} [f(x) \pm g(x)] = L_1 \pm L_2$$



$$2 - \text{Lim} [f(x)g(x)] = L1 \cdot L2$$

$$3 - \text{Lim} \left[ \frac{f(x)}{g(x)} \right] = \frac{L1}{L2} \text{ if } L2 \neq 0$$

$$4 - \text{Lim}_{x \rightarrow c} [K f(x)] = KL_1 \text{ Where K is a constant}$$

Theorem 2

$$1 - \text{Lim} K = K, \text{ K is constant}$$

$$2 - \text{Lim}_{x \rightarrow c} [a_0 + a_1x + a_2x^2 + \dots + a_nx^n] = a_0 + a_1c + a_2c^2 + \dots + a_nc^n$$

$$3 - \text{Lim}_{x \rightarrow 0} \sin x = 0$$

$$4 - \text{Lim}_{x \rightarrow 0} \cos x = 1$$

$$5 - \text{Lim}_{x \rightarrow 0} \frac{\sin x}{x} = 1$$

Example: Evaluate

$$1 - \text{Lim}_{x \rightarrow 2} (4x^2) = 4 \text{Lim}_{x \rightarrow 2} x^2 = 4(2)^2 = 16$$

$$2 - \text{Lim}_{x \rightarrow 2} (x^2 - 9) = 4 - 9 = -5$$

$$3 - \text{Lim}_{x \rightarrow 2} \frac{x^3 - 8}{x^2 - 4} = \frac{(x-2)(x^2 + 2x + 4)}{(x-2)(x+2)} = \frac{x^2 + 2x + 4}{x+2}$$

$$= \frac{12}{4} = 3$$

$$4 - \text{Lim}_{x \rightarrow 0} \frac{\sin x}{x} = 3 \text{Lim}_{3x \rightarrow 0} \frac{\sin 3x}{3x} = 3(1) = 3$$



$$\begin{aligned}
5 - \lim_{\chi \rightarrow 0} \frac{\tan \chi}{\chi} &= \frac{\sin \chi}{\cos \chi} \cdot \frac{1}{\chi} = \lim_{\chi \rightarrow 0} \left[ \frac{\sin \chi}{\cos \chi} \cdot \frac{1}{\chi} \right] \\
&= \lim_{\chi \rightarrow 0} \left[ \frac{\sin \chi}{\chi} \cdot \frac{1}{\cos \chi} \right] \\
&= \left[ \lim_{\chi \rightarrow 0} \frac{\sin \chi}{\chi} \right] \cdot \left[ \lim_{\chi \rightarrow 0} \frac{1}{\cos \chi} \right] = (1) (1) = 1
\end{aligned}$$

### Infinity as Limits

Evaluate:

$$1 - \lim_{X \rightarrow 0^+} \frac{1}{X} = \infty \quad (2) \quad \lim_{\chi \rightarrow 0^-} \frac{1}{\chi} = -\infty$$

$$3 - \lim_{x \rightarrow \infty} \frac{1}{x} = 0$$

$$4 - \lim_{x \rightarrow \infty} \frac{2x^2 - x + 3}{3x^2 - 5} = \lim_{x \rightarrow \infty} \frac{\frac{2x^2}{x^2}}{\frac{3x^2}{x^2} - \frac{5}{x^2}}$$

Theorem

If  $f(\chi) \leq g(\chi) \leq h(X)$  and  $\lim f(\chi) = \lim h(X) = L$  then

L is the limit of g(x)

Example: Evaluate

$$1 - \lim_{X \rightarrow \infty} \frac{\sin X}{X}$$

$$2 - \lim_{X \rightarrow \infty} \chi \sin\left(\frac{1}{X}\right)$$

### Continuity

Definition: A function  $f$  is said to be continuous at  $\chi = C$  provided the following conditions are satisfied:

- 1  $f(C)$  is defined
- 2  $\lim_{\chi \rightarrow C} f(x)$  exists
- 3  $\lim_{x \rightarrow C} f(x) = f(C)$

### Theorem

Any Polynomial

$$1 P(\chi) = a_0 + a_1\chi + a_2X^2 + \dots + anX^4 \quad (an \neq 0)$$

Is continuous for all  $\chi$

$$2 R(\chi) = \frac{a_0 + a_1X + a_2 X^2 + \dots + anX^4}{b_0 + b_1 X + b_2 X^2 + \dots + bnX^4} \quad (an \neq 0, bn \neq 0)$$

Is continuous at every point of its domain of definition that is at every point where its denominator is not zero

3 Each of the trigonometric functions  $\sin X$ ,  $\cos X$ ,  $\tan X$ ,  $\cot X$ ,  $\sec X$ , and  $\csc X$ , is continuous at every point of its domain of definition.

### Example 1

$$\lim_{X \rightarrow \pi} (\cos^2 X + \cos X + 1)$$

### Solution

$$\begin{aligned} \lim_{X \rightarrow \pi} (\cos^2 X + \cos X + 1) &= (\cos^2 \pi + \cos \pi + 1) \\ &= (-1)^2 - 1 + 1 = 1 \end{aligned}$$

### Example2

$$f(x) = \frac{|x|}{x} \text{ Discontinuous at } x = 0$$

$$\lim_{x \rightarrow 0^+} \frac{|x|}{x} = 1$$

$$x > 0$$

$$\lim_{x \rightarrow 0^-} \frac{|x|}{x} = -1$$

$$x < 0$$

$$\lim_{x \rightarrow 0} \frac{|x|}{x} \text{ does not exist}$$

$f(x)$  discontinuous

Example 3: check the continuity of the function  $x = 3$

$$f(x) = \begin{cases} x-2 & x \neq 3 \\ 1 & x = 3 \end{cases}$$

SOL

$$f(3) = 1$$

$$\lim_{x \rightarrow 3} (x-2) = 3-2=1$$

$$x \rightarrow 3$$

$$f(3) = \lim_{x \rightarrow 3} f(x)$$

The function continuous at  $x = 3$

### Problems

Q1// find Domain, range and sketch each of the following:

1 -  $y = x^2$

2 -  $y = \sqrt{x}$

3 -  $y = 1/x$

4 -  $y = |x + 2|$

5 -  $y = \frac{|x|}{x}$

6 -  $y = \frac{1}{x}$

$$7 - y = \frac{\chi+1}{\chi-1}$$

$$8 - y = 2 \sin \chi$$

$$9 - y = -2 \sin \chi$$

$$10 - y = 2 + \cos \chi$$

Q2 // Evaluate each of the following limits:

$$1 - \lim_{y \rightarrow 2} \frac{t+3}{t+2}$$

$$2 - \lim_{\chi \rightarrow 1} \frac{\chi^2 - 1}{\chi - 1}$$

$$3 - \lim_{y \rightarrow 2} \frac{y^2 + 5y + b}{y + 2}$$

$$4 - \lim_{y \rightarrow 2} \frac{y^2 - 5y + 6}{y - 2}$$

$$5 - \lim_{\chi \rightarrow -3} \frac{\chi^2 + 4\chi + 3}{\chi + 3}$$

$$6 - \lim_{t \rightarrow \infty} \frac{t+1}{t^2+1}$$

$$7 - \lim_{t \rightarrow \infty} \frac{t^2 - 2t}{2t^2 + 5t - 3}$$

$$8 - \lim_{\theta \rightarrow 0} \frac{\tan \theta}{\theta}$$

$$9 - \lim_{\theta \rightarrow 0} \frac{\sin 2\theta}{\theta}$$

$$10 - \lim_{\chi \rightarrow 0} \frac{\sin \chi}{3\chi}$$

$$11 - \lim_{\chi \rightarrow 0} \frac{\sin 5\chi}{\sin 3\chi}$$

$$12 - \lim_{\chi \rightarrow \infty} \chi \sin \frac{1}{\chi}$$

$$13 - \lim_{\chi \rightarrow 0} \frac{\sin^2 \chi}{\chi}$$

$$14 - \lim_{\chi \rightarrow 0} \frac{\sin^2 \chi}{2\chi^2 + \chi}$$

$$15 - \lim_{\chi \rightarrow 0} \tan 2\chi \csc 4\chi$$

## Chapter Three

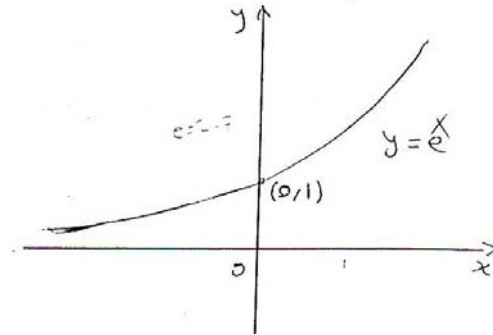
### Special Function

#### 1 - Exponential function

(i)  $y = e^x$ ,  $e = 2.7$

Domain:  $\mathbb{R}$

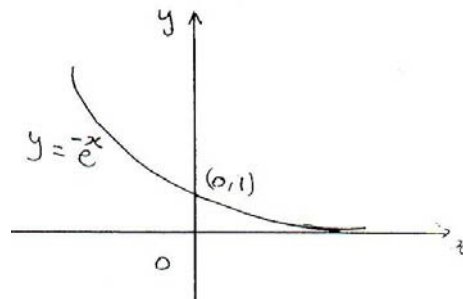
Range:  $\mathbb{R} (0, \infty)$



(ii)  $y = e^{-x}$

Domain:  $\mathbb{R}$

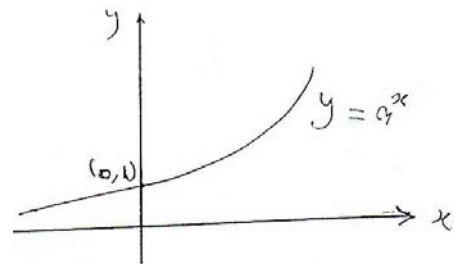
Range:  $\mathbb{R} (0, \infty)$



(iii)  $y = a^x$ ,  $a > 0$

Domain:  $\mathbb{R}$

Range:  $(0, \infty)$



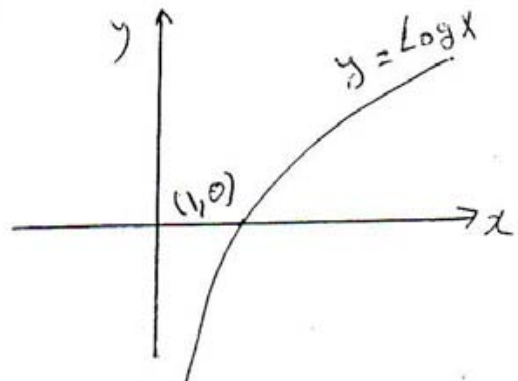
#### 2 - Logarithmic Function:

(i) Common logarithmic function ( $\text{Log } X$ )

$$y = \text{Log}_{10} X \Leftrightarrow X = 10^y$$

Domain:  $(0, \infty)$

Range:  $\mathbb{R}$

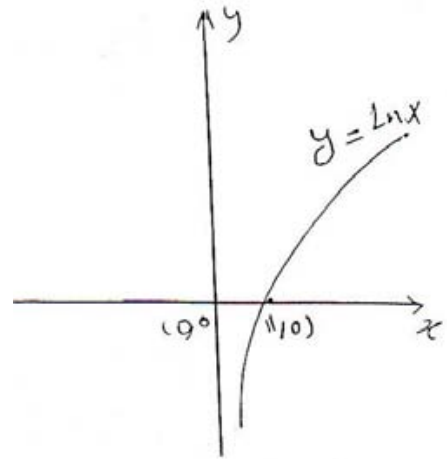


(ii) Natural Logarithmic function ( $\ln x$ )

$$y = \ln x \Leftrightarrow X = e^x, e = 2.7$$

Domain:  $(0, \infty)$

Range:  $\mathbb{R}$



**Theorem:**

If  $a$  and  $X$  are positive numbers and  $n$  is any rational number, then

(i)  $\ln 1 = 0$

(ii)  $\ln e = 1$

(iii)  $\ln aX = \ln a + \ln x$

(iv)  $\ln\left(\frac{X}{a}\right) = \ln X - \ln a$

(v)  $\ln X^n = n \ln X$ .

**Note:**

(1)  $e^{\ln X} = X \quad X > 0$

(2)  $\ln e^x = x$

(3)  $e^x e^y = e^{x+y}$

(4)  $\lim_{x \rightarrow \infty} \ln x = \infty$

(5)  $\lim_{x \rightarrow -\infty} e^x = 0$

(6)  $\ln x^a = a \ln x$

## Hyperbolic Functions:

The Hyperbolic Functions are certain combinations of the exponential

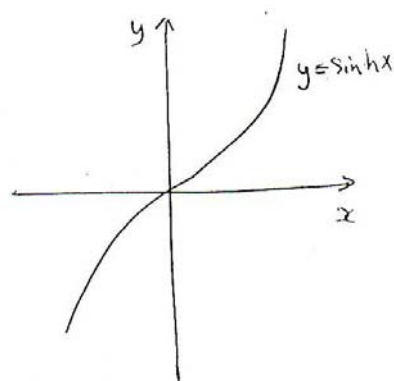
functions  $e^x$  and  $e^{-x}$  they are:

(i) Hyperbolic Sine (Sinh):

$$y = \text{Sinh}X, \text{Sinh}X = \frac{e^x - e^{-x}}{2}$$

Domain: R

Range: R

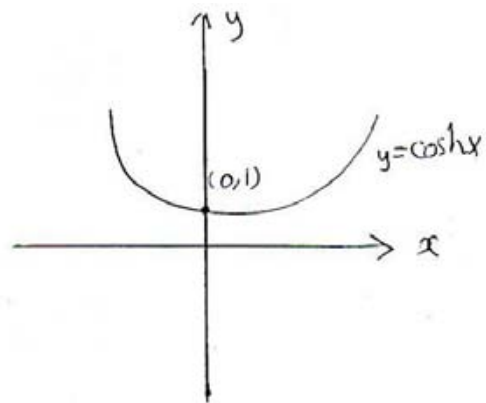


(ii) Hyperbolic Cosine (cosh)

$$y = \text{Cosh}x, \text{Cosh}X = \frac{e^x + e^{-x}}{2}$$

Domain: R

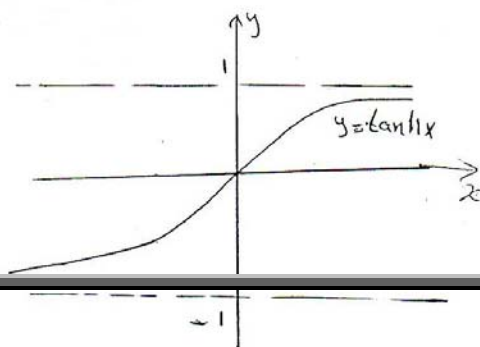
Range: (1, ∞)



(iii) Hyperbolic tangent (tanh)

$$y = \tanh x, \tanh x = \frac{e^x - e^{-x}}{e^x + e^{-x}}$$

Domain: R



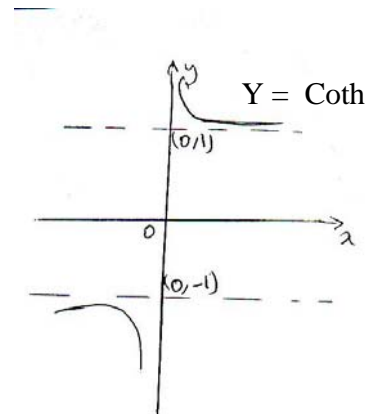
Range:  $(-1,1)$

(iv) Hyperbolic cotangent (coth)

$$y = \coth x, \quad \coth x = \frac{\frac{x}{e^x + e^{-x}}}{\frac{x}{e^x - e^{-x}}}$$

Domain:  $\mathbb{R} - \{0\}$

Range:  $\{y : y < -1 \text{ or } y > 1\}$

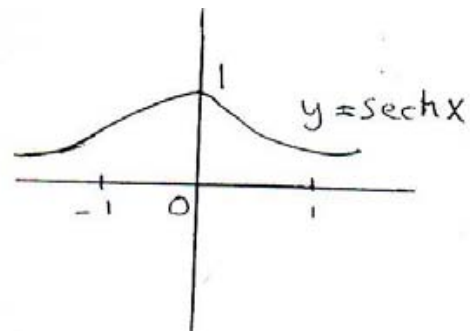


(v) Hyperbolic Secant (Sech)

$$y = \operatorname{sech} x, \quad \operatorname{sech} x = \frac{2}{\frac{x}{e^x + e^{-x}}}$$

Domain:  $\mathbb{R}$

Range:  $(0,1)$

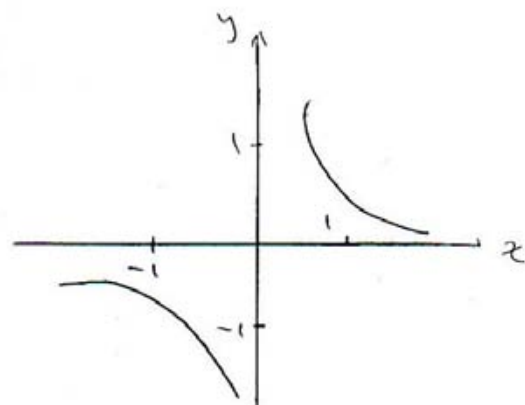


(vi) Hyperbolic cosecant (Csch)

$$y = \operatorname{csch} x, \quad \operatorname{csch} x = \frac{2}{\frac{x}{e^x - e^{-x}}}$$

Domain:  $\mathbb{R} - \{0\}$

Range:  $\mathbb{R} - \{0\}$





## Relationships among

### Hyperbolic Function

$$1 - \cosh^2 \chi - \sinh^2 \chi = 1$$

$$2 - \operatorname{sech}^2 \chi + \tanh^2 \chi = 1$$

$$3 - \operatorname{coth}^2 \chi - \operatorname{csch}^2 \chi = 1$$

### Functions of negative arguments

$$1 - \sinh(-\chi) = -\sinh \chi$$

$$2 - \cosh(-\chi) = \cosh \chi$$

$$3 - \tanh(-\chi) = -\tanh \chi$$

$$4 - \operatorname{coth}(-\chi) = -\operatorname{coth} \chi$$

$$5 - \operatorname{sech}(-\chi) = \operatorname{sech} \chi$$

$$6 - \operatorname{csch}(-\chi) = -\operatorname{csch} \chi$$

### Addition Formula:

$$1 - \sinh(\chi \pm y) = \sinh \chi \cosh y \pm \cosh \chi \sinh y$$

$$2 - \cosh(\chi \pm y) = \cosh \chi \cosh y \pm \sinh \chi \sinh y$$

### Double angle formula:

$$1 - \sinh 2\chi = 2\sinh \chi \cosh \chi$$

$$\cosh 2\chi = \cosh^2 \chi + \sinh^2 \chi$$

$$2 - \sinh^2 \chi = 1 + 2\sinh^2 \chi$$

$$\cosh^2 \chi = 2 \cosh^2 \chi - 1$$

### Inverse Trigonometric Function

#### 1 – Inverse Sine ( $\sin^{-1}$ )

$$y = \sin^{-1} \chi = \arcsin \chi \Leftrightarrow \chi = \sin y.$$

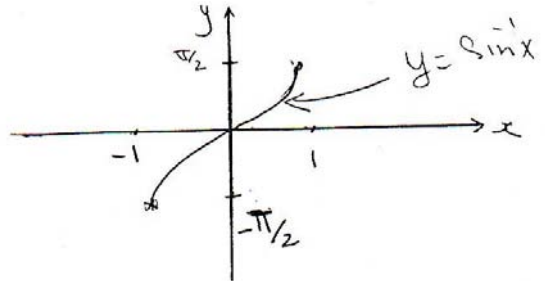
Y is the angle whose Sine is  $\chi$

Example:

$$45^\circ = \text{Sin}^{-1} \frac{1}{\sqrt{2}}, \frac{\pi}{2} = \text{Sin}^{-1} 1$$

Domain:  $[-1, 1]$

Range:  $\left[-\frac{\pi}{2}, \frac{\pi}{2}\right]$  Principle values of y.



2 – Inverse Cosine ( $\text{Cos}^{-1}$ )

$$y = \text{Cos}^{-1} \chi = \text{arc Cos} \chi \rightarrow \chi = \text{Cos} y$$

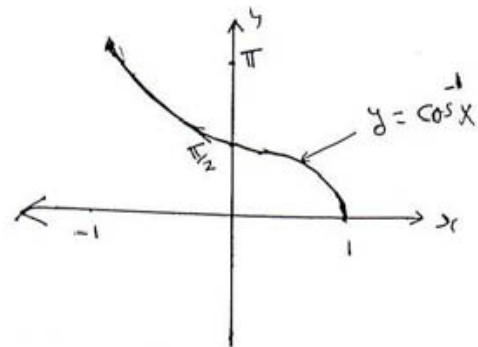
y is the angle whose cosin is  $\chi$

Example:

$$30^\circ = \text{Cos}^{-1} \frac{\sqrt{3}}{2} \rightarrow \frac{\sqrt{3}}{2} = \text{Cos} 30^\circ$$

Domain:  $[-1, 1]$

Range:  $[0, \pi]$



3 – Inverse of tangent ( $\text{tan}^{-1}$ )

$$y = \text{tan}^{-1} \chi = \text{arc tan} \chi \Leftrightarrow \chi = \text{tan} y$$

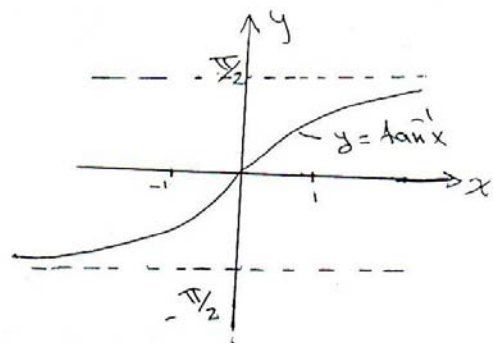
y = is the angle whose cosin is  $\chi$

Example:

$$45^\circ = \text{tan}^{-1} 1 \Leftrightarrow 1 = \text{tan} 45$$

Domain:  $\mathbb{R}$

Range:  $\left(-\frac{\pi}{2}, \frac{\pi}{2}\right)$

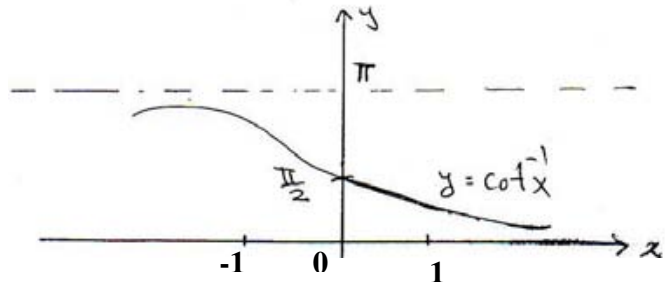


#### 4 – Inverse of cotangent ( $\text{Cot}^{-1}$ )

$$y = \text{Cot}^{-1} \chi = \text{arc Cot } \chi \Leftrightarrow \chi = \text{Coty}$$

Domain:  $\mathbb{R}$

Range:  $(0, \pi)$

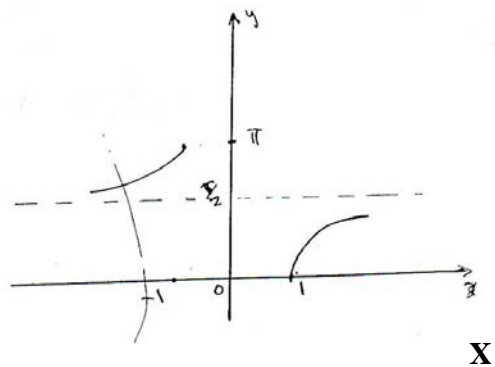


#### 5 – Inverse secant ( $\text{Sec}^{-1}$ )

$$y = \text{Sec}^{-1} \chi = \text{arc Sec } \chi \rightarrow \chi = \text{Sec } y$$

Domain:  $(-\infty, -1] \cup [1, +\infty)$

Range:  $\left[0, \frac{\pi}{2}\right) \cup \left(\frac{\pi}{2}, \pi\right]$

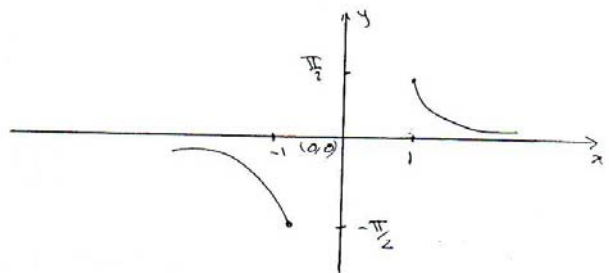


#### 6 – Inverse Csc ( $\text{Csc}^{-1}$ )

$$y = \text{Csc}^{-1} \chi = \text{arc Csc } \chi \Leftrightarrow \chi = \text{Csc } y$$

Domain:  $(-\infty, -1] \cup [1, \infty)$

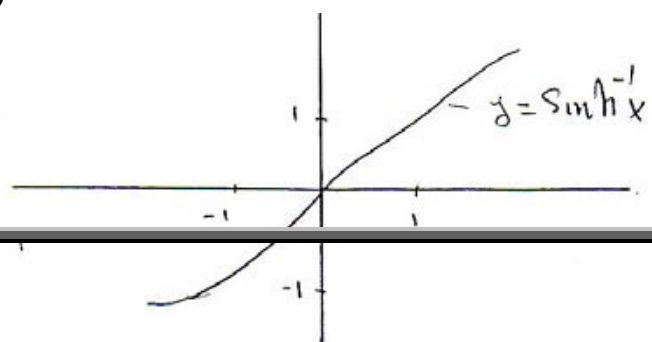
Range:  $\left[-\frac{\pi}{2}, 0\right) \cup \left(0, \frac{\pi}{2}\right]$



### Inverse hyperbolic Functions

#### 1 – Inverse hyperbolic sine ( $\text{Sinh}^{-1}$ )

$$y = \text{Sinh}^{-1} \chi \Leftrightarrow \chi = \text{Sinhy}$$



Domain:  $\mathbb{R}$

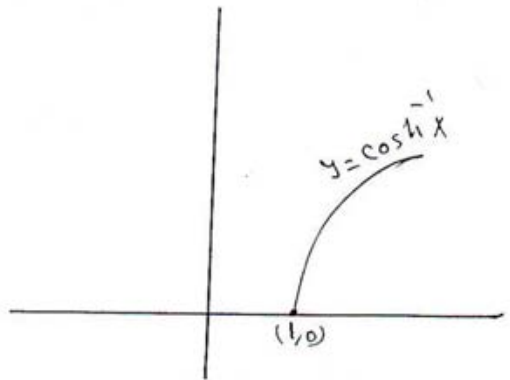
Range:  $\mathbb{R}$

2 - Inverse hyperbolic cosin ( $\text{Cosh}^{-1}$ )

$$y = \text{Cosh}^{-1} \chi \Leftrightarrow \chi = \text{Cosh} y$$

Domain:  $[1, \infty)$

Range:  $[0, \infty)$

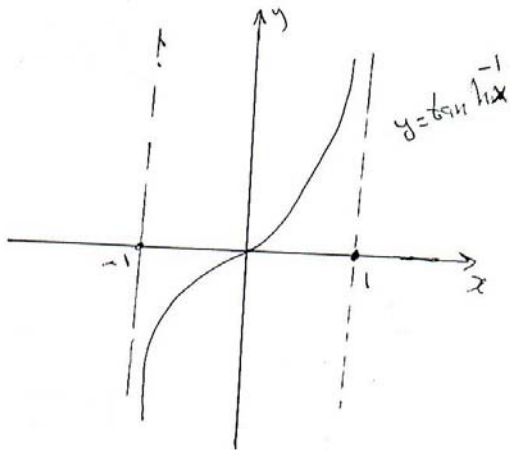


3 - Inverse hyperbolic tangent ( $\text{tanh}^{-1}$ )

$$y = \text{tanh}^{-1} \chi \Leftrightarrow \chi = \text{tanh} y$$

Domain:  $(-1, 1)$

Range:  $\mathbb{R}$

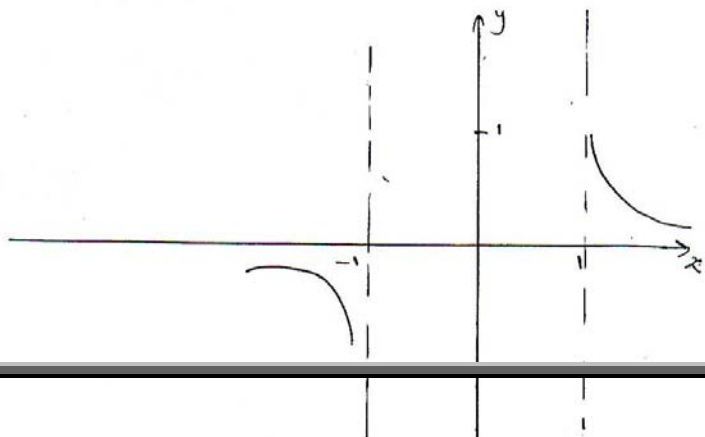


4 - Inverse hyperbolic cotangent ( $\text{Coth}^{-1}$ )

$$y = \text{Coth}^{-1} \chi \Leftrightarrow \chi = \text{Coth} y$$

Domain:  $\{x \mid |x| > 1\}$

Range:  $\mathbb{R} \setminus \{0\}$

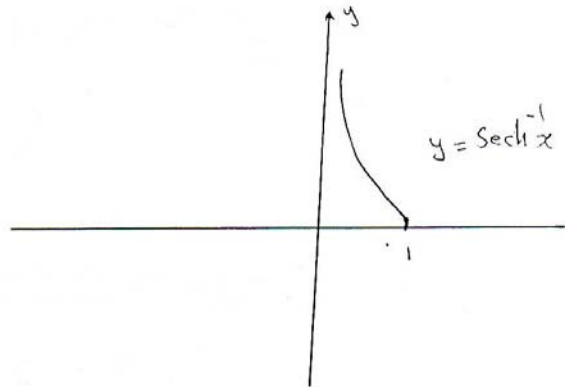


### 5 – Inverse hyperbolic secant (Sech -1)

$$y = \operatorname{sech}^{-1} \chi \Leftrightarrow \chi = \operatorname{sech} y$$

Domain:  $(0, 1]$

Range:  $y \geq 0$



### 6 – Inverse hyperbolic cosecant (Csch -1)

$$y = \operatorname{csch}^{-1} \chi \Leftrightarrow \chi = \operatorname{csch} y$$

### Logarithmic Form of Inverse hyperbolic Functions

Theorem: the following relationships hold for all  $\chi$  in the domain of the stated inverse hyperbolic.

Functions:

$$1 - \operatorname{Sinh}^{-1} = \operatorname{Ln}(\chi + \sqrt{\chi^2 + 1})$$

$$2 - \operatorname{Cosh}^{-1} \chi = \operatorname{Ln}(\chi + \sqrt{\chi^2 - 1})$$

$$3 - \tanh^{-1}\chi = \frac{1}{2} \operatorname{Ln} \left( \frac{1+\chi}{1-\chi} \right)$$

$$4 - \operatorname{Coth}^{-1}\chi = \frac{1}{2} \operatorname{Ln} \left( \frac{\chi+1}{\chi-1} \right)$$

$$5 - \operatorname{Sech}^{-1}\chi = \operatorname{Ln} \left( \frac{1+\sqrt{1-\chi^2}}{\chi} \right)$$

$$6 - \operatorname{Csch}^{-1}\chi = \operatorname{Ln} \left( \frac{1}{\chi} + \frac{\sqrt{1+\chi^2}}{|\chi|} \right)$$

Prove that:

$$* \operatorname{Sinh}^{-1}\chi = \operatorname{Ln}(\chi + \sqrt{\chi^2 + 1})$$

Sol

Let  $y = \operatorname{Sinh}^{-1}\chi$

$$* \chi = \operatorname{Sinhy} \text{ Since } \operatorname{Sinhy} = \frac{e^y - e^{-y}}{z}$$

$$X = \frac{e^y - e^{-y}}{z} \rightarrow 2X = e^y - e^{-y}$$

$$\left( e^y - z\chi - e^{-y} = 0 \right) e^y \rightarrow e^{2y} - 2\chi e^y - 1 = 0$$

$$e^y = \frac{2\chi \pm \sqrt{4\chi^2 + 4}}{2} = \chi \pm \sqrt{\chi^2 + 1}$$

Since  $e^y > 0$  then

$$e^y = \chi + \sqrt{\chi^2 + 1} \rightarrow y = \operatorname{Ln}(\chi + \sqrt{\chi^2 + 1}) \text{ or}$$

$$\operatorname{Sinh}^{-1}\chi = \operatorname{Ln}(\chi + \sqrt{\chi^2 + 1})$$

Example:

$$\begin{aligned} \operatorname{Sinh}^{-1} 1 &= \operatorname{Ln}(1 + \sqrt{1+1}) \\ &= \operatorname{Ln}(1 + \sqrt{2}) \\ &= 0.88 \end{aligned}$$

$$* \tanh^{-1} \chi = \frac{1}{2} \operatorname{Ln} \left( \frac{1 - \chi}{1 + \chi} \right)$$

Sol

$$\text{Let } y = \tanh^{-1} \chi$$

$$\therefore \chi = \tanh y = \frac{e^y - e^{-y}}{e^y + e^{-y}} \rightarrow \left[ (e^y + 1) \chi = e^y - e^{-y} \right] e^y$$

$$(e^y + 1) \chi = e^y - 1 \rightarrow \chi e^{2y} + \chi = e^y - 1$$

$$\chi + 1 = e^{2y} - \chi e^{2y} \rightarrow e^{2y} (1 - \chi) = 1 + \chi$$

$$e^{2y} = \frac{1 + \chi}{1 - \chi} \rightarrow 2y = \frac{1}{2} \operatorname{Ln} \left( \frac{1 + \chi}{1 - \chi} \right)$$

$$\tanh^{-1} \chi = \frac{1}{2} \operatorname{Ln} \left( \frac{1 + \chi}{1 - \chi} \right)$$

Example:

$$\begin{aligned} \tanh^{-1} \left( \frac{1}{2} \right) &= \frac{1}{2} \operatorname{Ln} \left( \frac{1 + \frac{1}{2}}{1 - \frac{1}{2}} \right) = \frac{1}{2} \operatorname{Ln} 3 = 0.5493 \\ &= 0.55 \end{aligned}$$

**Problems:**

Q1: find domain, range and sketch each of following:

$$1 - y = \operatorname{Sin}^{-1} \chi, \quad -\frac{\pi}{2} \leq y \leq \frac{\pi}{2}$$

$$2 - y = \operatorname{Cot}^{-1} \chi, \quad 0 < y < \pi$$

$$3 - y = \operatorname{tan}^{-1} \chi, \quad -\frac{\pi}{2} < y < \frac{\pi}{2}$$

$$4 - y = \csc^{-1} \chi, \quad -\frac{\pi}{2} < y < \frac{\pi}{2}$$

$$5 - y = \cot^{-1} \chi, \quad 0 < y < \pi$$

$$6 - y = \sec^{-1} \chi, \quad 0 \leq y \leq \pi$$

$$7 - y = 3 \ln \chi$$

$$8 - y = -3 \ln \chi$$

$$9 - y = 2 e^{3x}$$

$$10 - y = 2 e^{-3x}$$

$$11 - y = \sinh^{-1} \chi$$

$$12 - y = \cosh^{-1} \chi$$

$$13 - y = \cosh^{-1} \chi$$

$$14 - y = \tanh^{-1} \chi$$

$$15 - y = \coth^{-1} \chi$$

$$16 - y = \coth^{-1} \chi$$

$$17 - y = \operatorname{sech}^{-1} \chi$$

$$18 - y = \operatorname{csch}^{-1} \chi$$

Q2: Prove that:

$$1 - \sinh^{-1} \chi = \ln(\chi + \sqrt{\chi^2 + 1}), \quad -\infty < \chi < \infty$$

$$2 - \cosh^{-1} \chi = \ln(\chi + \sqrt{\chi^2 - 1}), \quad \chi \geq 1$$

$$3 - \tanh^{-1} \chi = \frac{1}{2} \ln\left(\frac{1+\chi}{1-\chi}\right), \quad |\chi| < 1$$

$$4 - \coth^{-1} \chi = \frac{1}{2} \ln\left(\frac{\chi+1}{\chi-1}\right), \quad |\chi| > 1$$

$$5 - \operatorname{sech}^{-1} \chi = \ln\left(\frac{1+\sqrt{1-\chi^2}}{\chi}\right), \quad 0 < \chi \leq 1$$



$$6 - \operatorname{Csch}^{-1} \chi = \operatorname{Ln} \left( \frac{1}{\chi} + \frac{\sqrt{1 + \chi^2}}{|\chi|} \right), \chi \neq 0$$

Q3// Discuss the Continuity of the following functions at the given points:

$$1 - f(\chi) = |\chi + 4| \text{ at } \chi = -4$$

$$2 - f(\chi) = \begin{cases} \sqrt{1 - \chi^2} & \text{if } 0 \leq \chi < 1 \\ 1 & \text{if } 1 \leq \chi < 2 \\ 2 & \text{if } \chi = 2 \end{cases} \text{ at } \chi = 0$$

$$3 - f(\chi) = \frac{|\chi|}{\chi} \text{ at } \chi = 0$$

$$f(\chi) = \begin{cases} \frac{1 - \operatorname{Cos} \chi}{\operatorname{Sin} 2\chi} & \text{for } \chi \neq 0 \end{cases}$$

$$4 - \frac{1}{2} \text{ for } \chi = 0 \text{ at } \chi = 0$$

$$5 - f(\chi) = \begin{cases} \chi - 2 & \text{for } \chi \neq 3 \\ 1 & \text{for } \chi = 3 \end{cases} \text{ at } \chi = 3$$

$$6 - f(\chi) = \begin{cases} \frac{\chi^3 - 8}{\chi^2 - 4} & \text{for } \chi \neq 2 \\ 0 & \text{for } \chi = 2 \end{cases} \text{ at } \chi = 2$$

$$7 - f(\chi) = \begin{cases} \operatorname{Sin} \pi \chi & 0 < \chi < 1 \\ \operatorname{Ln} x & 1 < \chi < 2 \\ & \text{at } \chi = 1 \end{cases}$$

$$8 - f(x) = \frac{x - |x|}{x} \text{ at } x = 2$$

$$f(x) = \begin{cases} |x - 3| \\ x - 3 \end{cases} \text{ for } x \neq 3$$

$$9 - \begin{matrix} 0 & \text{for } x = 3 \\ \text{at } x = 3 \end{matrix}$$

Q4 // Simplify each of the following:

$$1 - e^{\ln x}$$

$$2 - \ln(e^x)$$

$$3 - e^{-\ln(x^2)}$$

$$4 - \ln(e^{-x^2})$$

$$5 - \ln(e^{\frac{1}{x}})$$

$$6 - \ln(e^{\frac{1}{x}})$$

$$7 - e^{\ln(\frac{1}{x})}$$

$$8 - e^{-\ln(\frac{1}{x})}$$

$$9 - e^{\ln 2 + \ln x}$$

$$10 - e^{2\ln x}$$

$$11 - \ln(e^{x - x^2})$$

$$12 - \ln(x^2, e^{-2x})$$

$$13 - e^x + \ln X$$

$$14 - e^{\ln X} - 2\ln y$$

## Chapter Four

### The derivative

1 – Derivative of a function:

Let  $y = f(X)$  and let  $P(X_1, y_1)$  be fixed point on the curve, and  $Q$

$(X_1 + \Delta X, y_1 + \Delta y)$  is another point on the curve as see in the figure

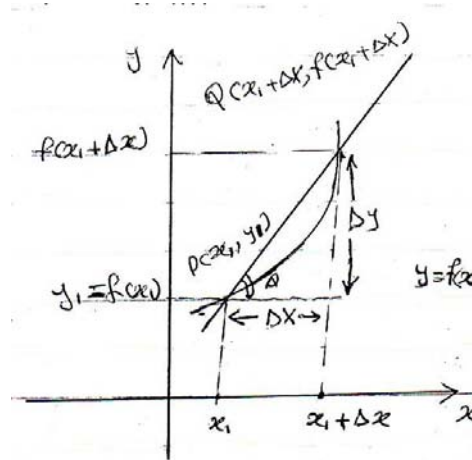
$y_1 = f(X_1)$ , and

$y_1 + \Delta y = f(X_1 + \Delta X)$

$\Delta y = f(X_1 + \Delta X) - y_1$

Divided by  $\Delta X$

$$\frac{\Delta y}{\Delta X} = \frac{f(X_1 + \Delta X) - f(X_1)}{\Delta X}$$



The

slope of the curve  $f(X)$  is

$$M = \tan \phi = \frac{\Delta y}{\Delta X}$$

$$\therefore M = \frac{f(X + \Delta X) - f(X)}{\Delta X}$$

We define the limit may exist for some value of  $X_1$  .

At each point  $x_1$  where limit does exist, then  $f$  is said to have a derivative or to be differentiable.

### Rules of Derivations:

$$y = f(X) = C$$

C constant

$$y' = f'(X) = \frac{dy}{dX} = 0$$

$$- f(X) = X^n$$

$$f'(X) = nX^{n-1}$$

$$- f(X) = CnX^{n-1}$$

$$- f(X) = U \pm V$$

n Positive integer

$$f'(X) = \frac{dy}{dX} = \frac{du}{dx} + \frac{dv}{dX}$$

$$- f(X) = UV$$

$$f'(X) = U \frac{dv}{dX} + V \frac{du}{dX}$$

$$- f(X) = \frac{u}{v}$$

$$f'(X) = \frac{vu' - uv'}{v^2}, \text{ Where } U' = \frac{du}{dX}$$

$$- f(X) = [U]^n$$

$$f'(X) = n[U]^{n-1} \frac{du}{dX}$$

$$- f(X) = e^u$$

$$f'(X) = e^u \frac{du}{dX}$$

$$- f(X) = C^u \quad U \quad C \text{ Constant}$$

$$f'(X) = C^u \cdot \ln C \cdot \frac{du}{dx}$$

Derivative of trigonometric functions:

- 1)  $(\sin u)' = \cos u \, du$
- 2)  $(\cos u)' = -\sin u \, du$
- 3)  $(\tan u)' = \sec^2 u \, du$
- 4)  $(\cot u)' = -\csc^2 u \, du$
- 5)  $(\sec u)' = \sec u \tan u \, du$
- 6)  $(\csc u)' = -\csc u \cot u \, du$

Derivative of hyperbolic functions:

- 1)  $\sinh u = \cosh u \, du$
- 2)  $\cosh u = \sinh u \, du$
- 3)  $\tanh u = \operatorname{sech}^2 u \, du$
- 4)  $\cot u = -\operatorname{csch}^2 u \, du$
- 5)  $\operatorname{sech} u = -\operatorname{sech} u \tanh u \, du$
- 6)  $\operatorname{csch} u = -\operatorname{csch} u \operatorname{coth} u \, du$

derivative of the inverse trigonometric functions:

- 1)  $(\sin^{-1}u)' = du/(1-u^2)^{1/2}$
- 2)  $(\cos^{-1}u)' = -du/(1-u^2)^{1/2}$
- 3)  $(\tan^{-1}u)' = du/1+u^2$
- 4)  $(\cot^{-1}u)' = -du/1+u^2$
- 5)  $(\sec^{-1}u)' = du/ u(u^2-1)^{1/2}$
- 6)  $(\csc^{-1}u)' = -du/ u(u^2-1)^{1/2}$

derivative of the inverse of hyperbolic functions:

- 1)  $(\sinh^{-1}u)' = du/(1+u^2)^{1/2}$
- 2)  $(\cosh^{-1}u)' = du/ (u^2-1)^{1/2}$
- 3)  $(\operatorname{coth}^{-1}u)' = du/1-u^2$  if  $|u|>1$
- 4)  $(\operatorname{tanh}^{-1}u)' = du/1-u^2$  if  $|u|<1$

$$5) (\operatorname{sech}^{-1}u)' = -du / u(1-u^2)^{1/2}$$

$$6) (\operatorname{csch}^{-1}u)' = -du / u(1+u^2)^{1/2}$$

ex: find  $y'$  of

$$(1) y = [\ln(3x+1)]^3 \quad (2) y = 4^x$$

Sol:

$$(1) y' = 3[\ln(3x+1)]^2 [3/(3x+1)] = 9[\ln(3x+1)]^2 / (3x+1)$$

$$(2) y' = 4^x \ln 4$$

{Applications of derivative}

Velocity and acceleration

Ex: find velocity and acceleration at time  $t$  to a moving body as

$$S = 2t^3 - 5t^2 + 4t - 3.$$

Sol:

$$V = ds/dt = 6t^2 - 10t + 4$$

$$A = dv/dt = 12t - 10$$

Theorem:

Prove that:

$$D(\sin^{-1}u) = 1/(1-u^2)^{1/2} (du/dx)$$

Proof

$$\text{Let } y = \sin^{-1} \rightarrow \sin y = u \quad u \in [-1, 1] \rightarrow y \in [-\pi/2, \pi/2]$$

$$\cos y \, dy/dx = du/dx \rightarrow dy/dx = 1/\cos y \, du/dx$$

Since  $\cos^2 y + \sin^2 y = 1$  this implies that

$$\cos y = (1 - \sin^2 y)^{1/2} \rightarrow \cos y = \pm (1 - u^2)^{1/2}$$

$\cos y$  is positive between  $-\pi/2$  and  $\pi/2$

$$Dy/dx = 1/(1-u^2)^{1/2} (du/dx) = D(\sin^{-1}u)$$

Ex: find  $dy/dx$  for the following functions:

$$(1) y = \tan(3x^2)$$

$$(2) y = x \sin^{-1} x + (1 - x^2)^{1/2}$$

$$(3) y = \cosh^{-1}(\sec x)$$

sol:

$$(1) y' = \sec^2(3x^2) 6x = 6x \sec^2(3x^2)$$

$$(2) y' = x/(1 - x^2)^{1/2} + \sin^{-1} x - x/(1 - x^2)^{1/2} = \sin^{-1} x$$

$$(3) y' = [1/(\sec^2 x - 1)^{1/2}] \sec x \tan x = \sec x \tan x / (\sec^2 x - 1)^{1/2}$$

### Implicit relations:

Ex: find dy/dx if

$$x^5 + 4x y^3 - 3y^5 = 2$$

sol:

$$5x^4 + 4x 3y^2(dy/dx) + 4y^3 - 15y^4(dy/dx) = 0$$

$$(12x y^2 - 15y^4) dy/dx = -5x^4 - 4y^3$$

$$dy/dx = (-5x^4 - 4y^3)/(12x y^2 - 15y^4)$$

### Chain Rule

1- If  $y = f(x)$ , and  $x = x(t)$ , then

$$\frac{\partial y}{\partial t} = \frac{\partial y}{\partial x} \frac{\partial x}{\partial t}$$

2- If  $y = f(t)$ , and  $x = x(t)$ , then

$$\frac{\partial y}{\partial x} = \frac{\frac{\partial y}{\partial t}}{\frac{\partial x}{\partial t}}$$

Ex: find  $\frac{dy}{dt}$ ,  $\frac{dx}{dt}$  and  $\frac{dy}{dx}$  of  $x = 3t + 1$  and  $y = t^2$

Sol:

$$\frac{dx}{dt} = 3, \quad \frac{dy}{dt} = 2t, \quad \frac{dy}{dx} = \frac{\frac{dy}{dt}}{\frac{dx}{dt}} = \frac{2t}{3}$$

### LHopital's Rule



Let  $f$  and  $g$  be two functions which are differentiable in an open interval  $I$  containing the point  $c$  and let  $g'(x) \neq 0$ . if

$$\lim_{x \rightarrow c} \frac{f(x)}{g(x)} = \frac{0}{0}, \frac{\infty}{\infty}, 0 \cdot \infty, \infty \cdot \infty, \infty \cdot \infty, \frac{\infty}{0}, \infty^0, \text{ then}$$

$$\lim_{x \rightarrow c} \frac{f(x)}{g(x)} = \lim_{x \rightarrow c} \frac{f'(x)}{g'(x)}.$$

Ex: evaluate (1)  $\lim_{x \rightarrow 0} \frac{x^2 - \sin x}{x^2}$ , (2)  $\lim_{x \rightarrow 0} x \ln x$

Sol:

$$(1) \lim_{x \rightarrow 0} \frac{x^2 - \sin x}{x^2} = \frac{0 - 0}{0} = \frac{0}{0}$$

$$\lim_{x \rightarrow 0} \frac{x^2 - \sin x}{x^2} = \lim_{x \rightarrow 0} \frac{2x - \cos x}{2x} = \frac{-1}{0} = \infty$$

$$(2) \lim_{x \rightarrow 0} x \ln x = 0 \cdot \infty$$

$$\lim_{x \rightarrow 0} x \ln x = \lim_{x \rightarrow 0} \frac{\ln x}{\frac{1}{x}} = \frac{\infty}{\infty}$$

$$\lim_{x \rightarrow 0} \frac{\ln x}{\frac{1}{x}} = \lim_{x \rightarrow 0} \frac{\frac{1}{x}}{\frac{-1}{x^2}} = \lim_{x \rightarrow 0} x = 0$$

## Series

(Power series): If  $\{a_n\}$  is a sequence of constants, the expression:

$$a_0 + a_1x + a_2x^2 + a_3x^3 + \dots + a_nx^n + \dots = \sum_{n=0}^{\infty} a_n x^n$$

is called power series in  $x$ .

(Taylor's series): If a function  $f$  can be represented by a power series in  $(x-b)$  called Taylor's series and has the form:

$$f(x) = f(b) + f'(b)(x-b) + \frac{f''(b)(x-b)^2}{2!} + \dots + \frac{f^{(n)}(b)(x-b)^n}{n!} + \dots$$

Example:

Find Taylor series expansion of  $\cos x$  about a point  $a=2\pi$

Sol:

$$f(x) = \cos x$$

$$f(2\pi) = \cos(2\pi) = 1$$

$$f'(x) = -\sin x, \quad f'(2\pi) = -\sin 2\pi = 0$$

$$f''(x) = -\cos x, \quad f''(2\pi) = -\cos 2\pi = -1$$

$$f'''(x) = \sin x, \quad f'''(2\pi) = \sin 2\pi = 0$$

$$f^{iv}(x) = \cos x, \quad f^{iv}(2\pi) = \cos 2\pi = 1$$

$$\cos x = 1 - \frac{(x-2\pi)^2}{2!} + \frac{(x-2\pi)^4}{4!} - \frac{(x-2\pi)^6}{6!} + \dots$$

(Maclaurin series): when  $b = 0$ , Taylor series called Maclaurin series.

Example:

Find Maclaurin series for the function  $f(x) = e^x$

Sol:

$$f(x) = e^x \rightarrow f(0) = e^0 = 1$$

$$f'(x) = e^x \rightarrow f'(0) = e^0 = 1$$

$$f''(x) = e^x \rightarrow f''(0) = e^0 = 1$$

$$f'''(x) = e^x \rightarrow f'''(0) = e^0 = 1$$

$$e^x = 1 + x + \frac{x^2}{2!} + \frac{x^3}{3!} + \dots$$

## Chapter five

### (INTEGRALS)

The process of finding the function whose derivative is given is called integration, it's the inverse of differentiation.

Definition:(indefinite integral)

A function  $y=F(x)$  is called a solution of  $dy/dx=f(x)$  if  $dF(x)/dx=f(x)$ .

We say that  $F(x)$  is an integral of  $f(x)$  with respect to  $x$  and  $F(x) + c$  is also an integral of  $f(x)$  with a constant  $c$  s.t

$$D(F(x) + c)=f(x).$$

Formulas of Integration:

- 1)  $\int dx=x + c.$
- 2)  $\int a dx=a \int dx$
- 3)  $\int (du \pm dv)= \int du \pm \int dv.$
- 4)  $\int x^n dx=(x^{n+1}/n+1)+ c$
- 5)  $\int (u)^n du=(u^{n+1}/n+1)+ c$
- 6)  $\int e^u du= e^u+ c$
- 7)  $\int a^u du=(a^u/\ln a) + c$
- 8)  $\int du/u= \ln u + c.$

Example 1:

Solve the differential equation:  $dy/dx=3x^2.$

Sol:

$$dy=3x^2 dx$$

since  $d(x^3)=3x^2 dx$ , then we have:

$$\int dy= \int 3x^2 dx= \int d(x^3) dx$$

$$y= x^3+ c.$$

9 methods for finding integrals:

1"Integral of trigonometric functions":

- 1)  $\int \cos u \, du = \sin u + c$
- 2)  $\int \sin u \, du = -\cos u + c$
- 3)  $\int \sec^2 u \, du = \tan u + c$
- 4)  $\int \csc^2 u \, du = -\cot u + c$
- 5)  $\int \sec u \tan u \, du = \sec u + c$
- 6)  $\int \csc u \cot u \, du = -\csc u + c$

2"Integral of hyperbolic functions":

- 1)  $\int \cosh u \, du = \sinh u + c$
- 2)  $\int \sinh u \, du = \cosh u + c$
- 3)  $\int \operatorname{sech}^2 u \, du = \tanh u + c$
- 4)  $\int \operatorname{csch}^2 u \, du = -\cot u + c$
- 5)  $\int \operatorname{sech} u \tanh u \, du = -\operatorname{sech} u + c$
- 6)  $\int \operatorname{csch} u \operatorname{coth} u \, du = -\operatorname{csch} u + c$

Integral of the inverse trigonometric functions:

- 1)  $\int \frac{du}{(1-u^2)^{1/2}} = \{ \sin^{-1}u + c \text{ or } -\cos^{-1}u + c \}$
- 2)  $\int \frac{du}{1+u^2} = \{ \tan^{-1}u + c \text{ or } -\cot^{-1}u + c \}$
- 3)  $\int \frac{du}{u(u^2-1)^{1/2}} = \sec^{-1}u + c \text{ or } -\csc^{-1}u + c \}$

Integral of the inverse of hyperbolic functions:

- 1)  $\int \frac{du}{(1+u^2)^{1/2}} = \sinh^{-1}u + c$
- 2)  $\int \frac{du}{(u^2-1)^{1/2}} = \cosh^{-1}u + c$
- 3)  $\int \frac{du}{1-u^2} = \tanh^{-1}u + c$  if  $|u| < 1$  and  $\int \frac{du}{1-u^2} = \operatorname{coth}^{-1}u + c$  if  $|u| > 1$
- 4)  $\int \frac{du}{u(1-u^2)^{1/2}} = -\operatorname{sech}^{-1}u + c$
- 5)  $\int \frac{du}{u(1+u^2)^{1/2}} = -\operatorname{csch}^{-1}u + c$

ex:

evaluate:

1)  $\int (5x^4 - 6x^2 + 2/x^2) dx$

2)  $\int \cos 2x dx$

3)  $\int \cos^2 x dx$

sol:

1)  $\int (5x^4 - 6x^2 + 2/x^2) dx = 5 \int x^4 dx - 6 \int x^2 dx + 2 \int x^{-2} dx$

$x^5 - 2x^3 - 2/x + c$

2)  $\int \cos 2x dx = \sin 2x/2 + c$

3)  $\int \cos^2 x dx = 1/2 \int (1 + \cos 2x) dx = 1/2 [\int dx + \int \cos 2x dx]$

$1/2 [x + \sin 2x/2] + c = 1/2x + 1/4 \sin 2x + c$

### 3- "Integration by parts"

Let  $u$  and  $v$  be functions of  $x$  and  $d(uv) = u dv + v du$

By integration both sides of this equation (w.r.t  $x$ )

$\int d(uv) = \int u dv + \int v du$  this implies  $(uv) = \int u dv + \int v du$

$\int u dv = (uv) - \int v du$

ex: find  $\int x e^x dx$

sol:

let  $u=x \rightarrow du = dx$  and let  $dv = e^x dx$

from  $\int u dv = (uv) - \int v du \rightarrow \int x e^x dx = x e^x - e^x + c$

### 4- "Integrals involving $(a^2 - u^2)^{1/2}$ , $(a^2 + u^2)^{1/2}$ , $(u^2 - a^2)^{1/2}$ , $a^2 - u^2$ , $a^2 + u^2$ ,

$u^2 - a^2$ "

(A)  $u = a \sin \Phi$  replaces  $a^2 - u^2 = a^2 - a^2 \sin^2 \Phi = a^2(1 - \sin^2 \Phi) =$

$a^2 \cos^2 \Phi$

(B)  $u = a \tan \Phi$  replaces  $a^2 + u^2 = a^2 + a^2 \tan^2 \Phi = a^2 \sec^2 \Phi$

(C)  $u = a \sec \Phi$  replaces  $u^2 - a^2 = a^2 \sec^2 \Phi - a^2 = a^2 \tan^2 \Phi$

Ex: find  $\int dx/x^2(4-x^2)^{1/2}$

Sol:

Let  $x=2\sin \Phi \rightarrow dx = 2\cos \Phi d\Phi$

$$\int dx/x^2(4-x^2)^{1/2} = \int 2\cos \Phi d\Phi/4 \sin^2 \Phi(4-4\sin^2 \Phi)^{1/2} =$$

$$\int 2\cos \Phi d\Phi/4 \sin^2 \Phi(2\cos \Phi) = \int d\Phi/4 \sin^2 \Phi = 1/4 \int \csc^2 \Phi d\Phi = -1/4 \cot \Phi + c$$

now

$$\text{from } x=2\sin \Phi \rightarrow \sin \Phi = x/2 \rightarrow \cos \Phi = (1-x^2/4)^{1/2} = 1/2(4-x^2)^{1/2}$$

$$-1/4 \cot \Phi + c = (-1/4)(4-x^2)^{1/2}/x$$

### 5-" Integrals involving $ax^2 + bx + c$ "

First, We put the equation as  $(ax^2 + bx) + c$ .

Second, if  $a \neq 1$ , we take  $a$  as a mutable by the sides of the equation which has  $x$ ,  $a[x^2 + (b/a)x] + c$ .

Third, put and sub to the equation  $[(1/2) \text{ the number multiplied by } x]^2$ ,  $a[x^2 + (b/a)x + (1/4)(b/a)^2 - (1/4)(b/a)^2] + c$ .

Fourth, rewrite the equation as  $a[x^2 + (b/a)x + (1/4)(b/a)^2] + c - (1/4)(b^2/a)$

Last, the equation become  $a[x + (1/2)(b/a)]^2 + c - (1/4)(b^2/a)$  and suppose  $u = x + (1/2)(b/a)$  to become  $a[u]^2 + c - (1/4)(b^2/a)$

Ex: Find  $\int dx/(4x^2 + 4x + 2)$

Sol:

$$4x^2 + 4x + 2 = (4x^2 + 4x) + 2 = 4(x^2 + x) + 2 =$$

$$4[x^2 + x + (1/4) - (1/4)] + 2 = 4[x^2 + x + (1/4)] + 2 - 1 =$$

$$4[x + 1/2]^2 + 1.$$

$$\text{Let } u = x + 1/2 \rightarrow 4[x + 1/2]^2 + 1 = 4u^2 + 1.$$

$$\text{Since } u = x + 1/2 \rightarrow x = u - (1/2) \rightarrow dx = du$$

$$\int dx/(4x^2 + 4x + 2) = \int du/(4u^2 + 1) = 1/2 \int 2du/(4u^2 + 1) =$$

$$1/2 \tan^{-1}2u = 1/2 \tan^{-1}2(x+1/2).$$

### 6-"method of partial fractions"

If the integral of the form  $f(x)/g(x)$  s.t  $f(x)$  and  $g(x)$  are poly.

And degree of  $f(x) <$  degree of  $g(x)$  we can carry out two cases:

Case i

If all factor of  $g(x)$  are linear, by the following ex:

Ex: find  $\int dx/ x^2 + x - 2$

Sol:

$$1/ x^2 + x - 2 = 1/(x-1)(x+2) = A/(x-1) + B/(x + 2) =$$

$$[A(x + 2) + B/(x - 1)] / (x-1) (x + 2)$$

$$1 = Ax + A2 + Bx - B = (A+B)x + (A2-B)$$

$$1 = A2 - B$$

$$0 = (A+B)$$

$$3A = 1 \rightarrow A = 1/3 \text{ put in eq.(2)} \rightarrow B = -1/3$$

$$\int dx/ x^2 + x - 2 = \int 1/(x-1)(x+2)dx = \int [A/(x-1) + B/(x + 2)]dx$$

$$= \int [(1/3)/(x-1) - (1/3)/(x + 2)]dx = 1/3 \int / (x-1) - 1/3 \int / (x + 2)dx$$

$$= 1/3 \ln|x-1| - 1/3 \ln|x+2| + c$$

Case ii

If some of the factors of  $g(x)$  are quadratic, by the following ex:

Ex: find  $\int (x^2 + x - 2)dx/ (3x^3 - x^2 + 3x - 1)$

Sol:

$$(x^2 + x - 2) / (3x^3 - x^2 + 3x - 1) = (x^2 + x - 2)/ x^2(3x - 1) + (3x - 1)$$

$$= (x^2 + x - 2)/ (3x - 1) (x^2+1) = [A/(3x - 1)] + [(Bx + C)/ (x^2+1)]$$

$$= [A(x^2+1) + (Bx + C) (3x - 1)] / (3x - 1) (x^2+1)$$

$$x^2 + x - 2 = A(x^2+1) + (Bx + C) (3x - 1)$$

$$x^2 + x - 2 = (A + 3B) x^2 + (B + 3C) x + (A-C)$$

$$A + 3B = 1$$

$$B + 3C = 1$$

$$\underline{A - C = -2}$$

$$A = -7/5, B = 4/5, C = 3/5$$

$$(x^2 + x - 2)/(3x - 1)(x^2 + 1) = (-7/5)/(3x - 1) + [(4/5)x + (3/5)]/(x^2 + 1)$$

And

$$\int (x^2 + x - 2)dx / (3x - 1)(x^2 + 1) = (-7/5) \int dx / (3x - 1) +$$

$$(4/5) \int x dx / (x^2 + 1) + (3/5) \int dx / (x^2 + 1)$$

$$= -(7/15) \ln |3x - 1| + (2/5) \ln |x^2 + 1| + 3/5 \tan^{-1} x$$

### 7-"further substitutions"

Some integrals involving fractional powers of the variable  $x$  may be simplified by substitution  $x = u^n$  where  $n$  is the least common multiple of the denominators of the exponents.

Ex:

$$I = \int (x)^{1/2} dx / (1 + (x)^{1/3})$$

sol:

$$\text{let } x = u^6 \rightarrow dx = 6u^5 du$$

$$I = \int (u^6)^{1/2} (6u^5) du / (1 + (u^6)^{1/3}) = 6 \int u^3 u^5 du / (1 + u^2) = 6 \int u^8 du / (1 + u^2)$$

By long division

$$u^8 / (1 + u^2) = u^6 - u^4 + u^2 - 1 + (1 / (1 + u^2))$$

$$I = 6 \int u^8 du / (1 + u^2) = 6 \int [u^6 - u^4 + u^2 - 1 + (1 / (1 + u^2))] du$$

$$= (6/7) u^7 - (6/5) u^5 + 2 u^3 - 6u + 6 \tan^{-1} u + c$$

$$= (6/7) x^{7/6} - (6/5) x^{5/6} + 2 x^{1/2} - 6x^{1/6} + 6 \tan^{-1}(x^{1/6}) + c$$

### 8-"rational functions of sin x and cos x"

If the integral that is rational function of  $\sin x$  or  $\cos x$  or both, can be changed as following:

$$\text{Let } z = \tan(x/2)$$

$$x/2 = \tan^{-1} z \rightarrow x = 2 \tan^{-1} z \rightarrow dx = 2dz / (1 + z^2)$$

$$\cos(x/2) = 1 / (1 + z^2)^{1/2}, \sin(x/2) = z / (1 + z^2)^{1/2}$$



$$\sin x = 2 \sin(x/2) \cos(x/2) = 2z/(1+z^2)$$

$$\cos x = \cos^2(x/2) - \sin^2(x/2) = (1-z^2)/(1+z^2) \text{ from } [\cos(x/2 + x/2)]$$

ex: find  $I = \int dx/(1 - \sin x + \cos x)$

sol:

$$I = \int \frac{2dz/(1+z^2)}{(1 - [2z/(1+z^2)] + [(1-z^2)/(1+z^2)])}$$

$$= \int \frac{2dz/(1+z^2)}{(1+z^2 - 2z + 1 - z^2)/(1+z^2)}$$

$$= \int 2dz/(2-2z) = \int dz/(1-z) = -\ln|1-z| + c = -\ln|1-\tan(x/2)| + c$$

9-"evaluating integrals of the following types"

(A)  $\sin(mx) \sin(nx) = (1/2) [\cos(m-n)x - \cos(m+n)x]$

(B)  $\sin(mx) \cos(nx) = (1/2) [\sin(m-n)x + \sin(m+n)x]$

(C)  $\cos(mx) \cos(nx) = (1/2) [\cos(m-n)x + \cos(m+n)x]$

Ex:

$$\int 2\sin(4x) \sin(3x) dx = \int (2/2) [\cos(4-3)x - \cos(4+3)x] dx$$

$$= \int (\cos x - \cos 7x) dx = \sin x - (1/7)\sin 7x + c$$

{definite integral}

The definite integral like indefinite integral but there is a limit to

the integral like  $\int_a^b f(x) dx = F(b) - F(a)$ .

Ex: evaluate  $\int_0^3 x^3 dx$

Sol:

$$(3)^4/4 - 0 = 81/4$$

Applications of definite integral

{area under the curve}

Ex: find the area under  $\sin x$  bdd by  $x=0$  and  $x=2\pi$  and  $x$ -axis

Sol:

$$A = \int_0^{2\pi} \sin x \, dx = \int_0^{\pi} \sin x \, dx - \int_{\pi}^{2\pi} \sin x \, dx = (\cos \pi - \cos 0) + (\cos 2\pi - \cos \pi) = (-1 - 1) + (1 - (-1)) = 4$$

{ area between two curves }

Ex: find the area bdd by  $y=2-x^2$  and  $y=-x$

Sol:

$$Y = 2 - x^2 = y = -x$$

$$2 - x^2 = -x \rightarrow x^2 - x - 2 = 0 \rightarrow (x-2)(x+1) = 0 \rightarrow x=2, x=-1$$

$$A = \int_{-1}^2 [(2-x^2) - (-x)] dx = [2x - (x^3/3) + (x^2/2)]_{-1}^2 = 6.5$$

### Double integrals

When the integral have two signals of integral to two parameters  $x$  and  $y$  called double integral, like  $\int \int f(x,y) \, dx \, dy$ .

The benefit of like integrals is to find the volume of things.

Ex: find the volume of  $f(x,y) = x^2y$  limited by  $x=(1,3)$  and  $y=(1,2)$

$$\begin{aligned} \int_1^2 \int_1^3 x^2y \, dx \, dy &= \int_1^2 [(x^3/3)y \, dy]_1^3 = \int_1^2 [(3^3/3) - (1^3/3)]y \, dy \\ &= \int_1^2 [(27/3) - (1/3)]y \, dy = \int_1^2 (26/3)y \, dy = (26/3) \int_1^2 y \, dy \\ &= [(26/3)(y^2/2)]_1^2 = [(13/3) y^2]_1^2 = (13/3) 4 - (13/3) = 13 \end{aligned}$$

